THEORETICAL MODEL

$$\begin{array}{l} \partial_{t}A_{1} = \mathbf{L}_{1}A_{1} + A_{1}[1 - |A_{1}|^{2} - g_{+}|A_{2}|^{2} - g_{-}|A_{3}|^{2}] \\ \partial_{t}A_{2} = \mathbf{L}_{2}A_{2} + A_{2}[1 - |A_{2}|^{2} - g_{+}|A_{3}|^{2} - g_{-}|A_{1}|^{2}] \\ \partial_{t}A_{3} = \mathbf{L}_{3}A_{3} + A_{3}[1 - |A_{3}|^{2} - g_{+}|A_{1}|^{2} - g_{-}|A_{2}|^{2}] \end{array} \qquad \begin{array}{l} g_{\pm} = 1 + \mu \pm \delta \\ \mathcal{L}_{j} = \nabla^{2}, \ \partial_{x_{j}}^{2} \\ \mathcal{L}_{j} = \nabla^{2}, \ \partial_{x_{j}}^{2} \end{array}$$

 $\begin{cases} \delta = 0 \rightarrow \text{potential dynamics} \\ \delta \int dr \frac{\delta \int dF_{\text{BH}}}{\delta A^*} \cdot \int f(A)^* + \text{c.c.} = 0 \rightarrow \\ \text{nonrelaxational potential flow} \end{cases}$

ZERO-DIMENSIONAL SYSTEMS

$$\mathcal{L}_{j} = 0, \quad A_{j} = \sqrt{R_{j}(t)} e^{i\theta_{j}(t)}, \quad j = 1, 2, 3$$

$$\begin{array}{l} R_{1}^{\bullet}(t) = 2R_{1}\left[1 - R_{1} - (1 + \mu + \delta)R_{2} - (1 + \mu - \delta)R_{3}\right] \\ R_{2}^{\bullet}(t) = 2R_{2}\left[1 - R_{2} - (1 + \mu + \delta)R_{3} - (1 + \mu - \delta)R_{1}\right] \\ R_{3}^{\bullet}(t) = 2R_{3}\left[1 - R_{3} - (1 + \mu + \delta)R_{1} - (1 + \mu - \delta)R_{2}\right] \end{array} , \begin{array}{l} \theta_{1}^{\bullet} = 0 \\ \theta_{2}^{\bullet} = 0 \\ \theta_{2}^{\bullet} = 0 \\ \theta_{3}^{\bullet} = 0 \end{array}$$

- Equations for the real variables {R₁, R₂, R₃} instead of complex variables {A₁, A₂, A₃}
- Similar sets of equations proposed to study population competition dynamics

Stationary Solutions

• Null:
$$(R_1, R_2, R_3) = (0,0,0)$$

• Rhombus : $(R_1, R_2, R_3) = \left\{ \left\{ \frac{\mu + \delta}{\mu(\mu + 2) - \delta^2}, \frac{\mu - \delta}{\mu(\mu + 2) - \delta^2}, 0 \right\}, K \right\}$
• Rolls R: $(R_1, R_2, R_3) = \{(1,0,0), \dots\}$
• Hexagon H: $(R_1, R_2, R_3) = 1/(3+2\mu)$
 $\delta = -\mu$
KL
 $\delta = -\mu$
 KL
 kL
 kL
 $\mu = -3/2$
 M
 $(0,0,1)$

The Case $\mu = 0$

Orthogonality condition holds (δ μ = 0) ⇒ nonrelaxational potential flow

$$R_{j}^{e} = -\frac{\partial V}{\partial R_{j}} + \delta f_{j}, \quad j = 1, 2, 3$$
Relaxational part
$$R_{j}^{e} = -\frac{\partial V}{\partial R_{j}} + \delta f_{j}, \quad j = 1, 2, 3$$

$$R_{j}^{e}$$

$$R_{j}^$$

Equations of motion

$$x(t) = R_1(t) + R_2(t) + R_3(t) = \frac{1}{\left(\frac{1}{x_0} - 1\right)e^{-2t} + 1}$$

After $t = O(1) \Rightarrow x(t) \approx 1$ (asymptotic dynamics)

Eliminating for instance R₁:

$$\mathbf{R}_{2} = 2\delta \frac{\delta H}{\delta R_{3}}$$
Hamiltonian dynamics
$$H(R_{2}, R_{3}) = R_{2}R_{3}(1 - R_{2} - R_{3}) \equiv E \quad (\text{`energy'})$$

$$\mathbf{R}_{3} = -2\delta \frac{\delta H}{\delta R_{2}}$$

 $E = \frac{R_1(0)R_2(0)R_3(0)}{[R_1(0) + R_2(0) + R_3(0)]^3}$ (only depends on initial conditions)

Explicit solutions for the period of the orbits and the amplitudes

$$T(E) = \frac{2}{\delta\sqrt{b(a-c)}} K(q) = \frac{-\frac{3}{2\delta}\log E}{E \to 0} \times (1 + O(E))$$





Time-dependent energy

$$E(t) = \frac{R_1 R_2 R_3}{(R_1 + R_2 + R_3)^3} \to \frac{dE}{dt} = -4\mu f(t)E, \quad f(t) > 0$$

Motion occurs near the plane R₁+R₂+R₃=1 [after a transient time of order 1]



Period of the orbits is function of time

$$E(t) = E(0) \exp(-4\mu \int_{t_0}^t f(t') dt') \approx E(t_0) e^{-4\mu(t-t_0)}$$



Busse-Heikes Model with Noise

Period increasing with time is unphysical.
 Solution: addition of fluctuations

$$A_{1}^{k} = A_{1} [1 - |A_{1}|^{2} - (1 + \mu + \delta)|A_{2}|^{2} - (1 + \mu - \delta)|A_{3}|^{2}] + \xi_{1}(t)$$

$$A_{2}^{k} = A_{2} [1 - |A_{2}|^{2} - (1 + \mu + \delta)|A_{3}|^{2} - (1 + \mu - \delta)|A_{1}|^{2}] + \xi_{2}(t)$$

$$A_{3}^{k} = A_{3} [1 - |A_{3}|^{2} - (1 + \mu + \delta)|A_{1}|^{2} - (1 + \mu - \delta)|A_{2}|^{2}] + \xi_{3}(t)$$

White noise processes: $\langle \xi_i(t)\xi_j^*(t')\rangle = 2\varepsilon \delta(t-t')\delta_{ij}$

Noise prevents E(t) from decaying to zero.

Fluctuating period is established (but periodic on average)

$$E(t) \rightarrow \langle E \rangle \implies T(t) \rightarrow \langle T \rangle = T(\langle E \rangle)$$



 $\mu = 0.1, \, \delta = 1.3, \, \epsilon = 10^{-6}$

 $\varepsilon = 10^{-2} - 10^{-6}$

Average energy

$$P_{\rm st}(\mu=0) \propto \exp[-V(\mu=0)/\epsilon] \rightarrow P_{\rm st}(\mu) \propto \exp[-\Phi(\mu)/\epsilon] \approx \exp[-V(\mu)/\epsilon]$$

$$\mu \text{ small}$$
$$\langle E \rangle \cong \frac{\int_{0}^{\infty} dR_{1} \int_{0}^{\infty} dR_{2} \int_{0}^{\infty} dR_{3} E \exp(-V/\epsilon)}{\int_{0}^{\infty} dR_{1} \int_{0}^{\infty} dR_{2} \int_{0}^{\infty} dR_{3} \exp(-V/\epsilon)}$$

Saddle-point type integration: $\langle E \rangle \approx (\epsilon/\mu)^2, \epsilon \rightarrow 0, \mu$ small

$$\Rightarrow \quad \left\langle T \right\rangle = T(\left\langle E \right\rangle) \approx \frac{3}{\delta} \log(\mu/\epsilon)$$

ONE-DIMENSIONAL SYSTEMS

Three competing nonconserved real order parameters with short-range interactions

$$A_{1}^{2} = \partial_{xx}A_{1} + A_{1}[1 - A_{1}^{2} - (1 + \mu + \delta)A_{2}^{2} - (1 + \mu - \delta)A_{3}^{2}]$$

$$A_{2}^{2} = \partial_{xx}A_{2} + A_{2}[1 - A_{2}^{2} - (1 + \mu + \delta)A_{3}^{2} - (1 + \mu - \delta)A_{1}^{2}]$$

$$A_{3}^{2} = \partial_{xx}A_{3} + A_{3}[1 - A_{3}^{2} - (1 + \mu + \delta)A_{1}^{2} - (1 + \mu - \delta)A_{2}^{2}]$$

- Prothotypical nonpotential problem to study domain growth and dynamical scaling
- We focus on the region below the KL instability: coexistence of three stable homogeneous states under nonpotential dynamics (δ ≠ 0)

Dynamics of an Isolated Kink

Isolated kink moves due to nonpotential effects

 $V(\mu,\delta)=h(\mu) \delta + O(\delta^2)$



Multikink Configurations

Kink motion — annihilation — domain growth



Front motion due to: attractive interaction forces + nonpotential effects

$$\partial_t L(t) = \pm 2v(\mu, \delta) - \gamma \exp(-\mu^{1/2}L(t))$$

$$L(t) \sim t$$

$$L(t) \sim \log t$$

Domain Growth and Dynamical Scaling



TWO-DIMENSIONAL SYSTEMS

- We take real variables, isotropic diffusion terms and we focus on the region below the KL instability point
- Normal front velocity



$$v_n(\mathbf{r}, t ; \boldsymbol{\mu}, \delta) = -\kappa(\mathbf{r}, t) + v_p(\boldsymbol{\mu}, \delta)$$
$$v_p(\boldsymbol{\mu}, \delta) \sim \delta + O(\delta^2)$$

> nonpotential dynamics + formation of vertex points

POTENTIAL

NONPOTENTIA

 $\mu = 3, \delta = 0$

 $\mu = 3, \delta = 2$



Rotation angular velocity

$$\omega(\mu,\delta) \propto V_p^{1/2} \kappa_0^{3/2}$$





Critical distance for vertex annihilation



Consequence: coarsening will occur for system sizes $S \leq d_c$

Vertex Motion)

- For long times vertices diffuse through the system
- Vertex dynamics affected by the boundary conditions

- Even number of vertices: half 🔨 and half 즜
- Periodic BC: rotation
 - Correlated motions are observed

Null BC:

- No restrictions about the number of vertices
- Vertices may disappear through the egdes of the system
- No correlated motions observed



Null BC

Periodic BC



Domain Growth and Dynamical Scaling)

- $\delta = 0$ (potential limit) $\Rightarrow L(t) \sim t^{1/2} + dynamical scaling (3 fields)$
- $\delta \neq 0$ (nonpotential limit) $\Rightarrow L(t) \neq t^{1/2} + dynamical scaling (2 fields)$



Spatial-dependent Terms

- Alternative explanation for period stabilization
- Two kinds of differential operators

$$\mathfrak{L}_{j}, j=1,2,3 \begin{cases} \nabla^2 & \mathbf{ISOTROPIC} \\ (\mathbf{\hat{e}}_j \cdot \nabla)^2 & \mathbf{ANISOTROPIC} \ (\leftarrow \mathbf{NWS}, \mathbf{GOS \ terms}) \end{cases}$$

- We focus on the region beyond the KL instability point
- Dynamics depends on the type of spatial derivatives and on the size of µ

- μ small
 - Similar morphology of domains
 - Alternating period dominated by the KL instability
 - Intrinsic KL period stabilizes to a statistically constant value with both kinds of terms



- μ large
 - Different morphology of domains

• Intrinsic KL period $\begin{cases} \nabla^2: & \text{diverges with time} \\ (\hat{\mathbf{e}}_j \cdot \nabla)^2: \text{saturates to a constant value} \end{cases}$

Different alternating periods

