

# Wavelength Multistability in Lasers: The Effect of Spatial Hole Burning

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# Outline

I. Motivation

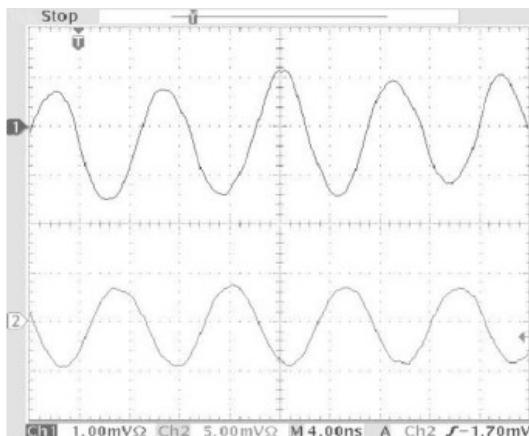
II. The model

III. Longitudinal modal multistability in lasers:  
Comparison between Ring and Fabry-Pérot configurations

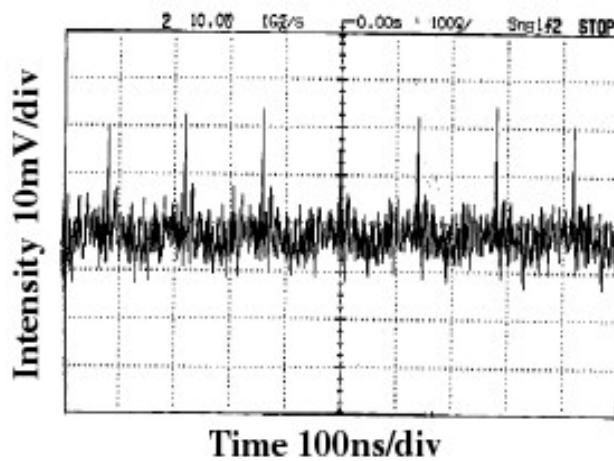
IV. Conclusions

# I. Motivation

- Ring Lasers can exhibit a rich variety of dynamical regimes:



Sorel et al.  
IEEE JQE **39**, 1187 (2003)

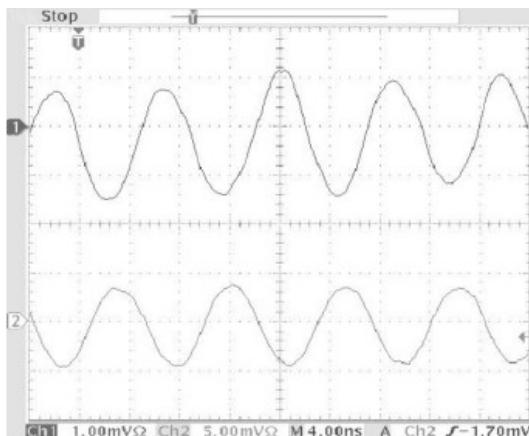


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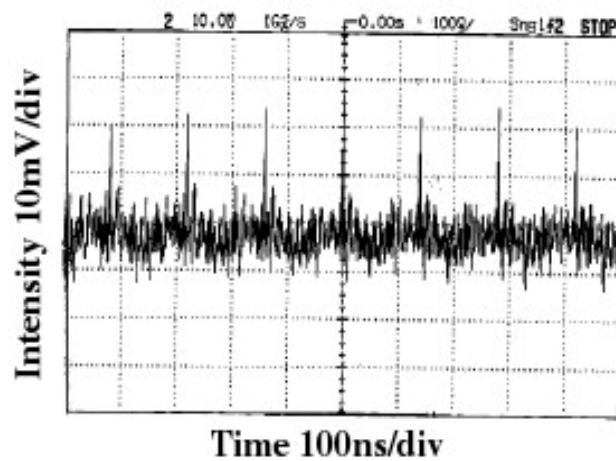
Bidirectional CW  
Alternate Oscillations  
Modelocking  
Bistability  
Chaos  
...

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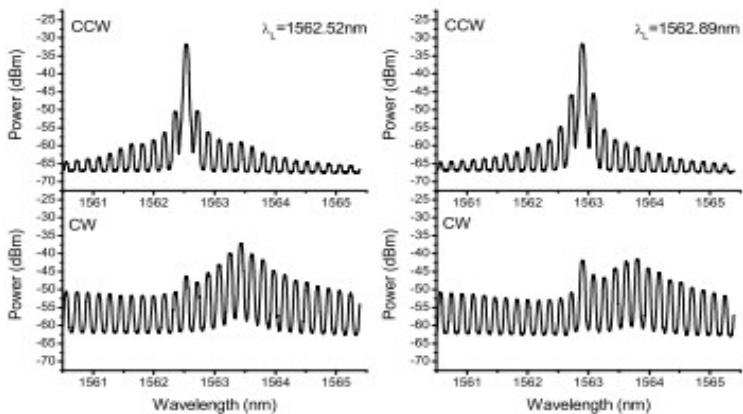
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...

Bistability in directional emission → **All-optical binary logics**

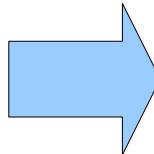
Hill et al. Nature **432**, 206 (2004)

# I. Motivation

- Experimental results show that in SRLs emission wavelength can be selected by optical injection, and the system remains stable at the chosen value.



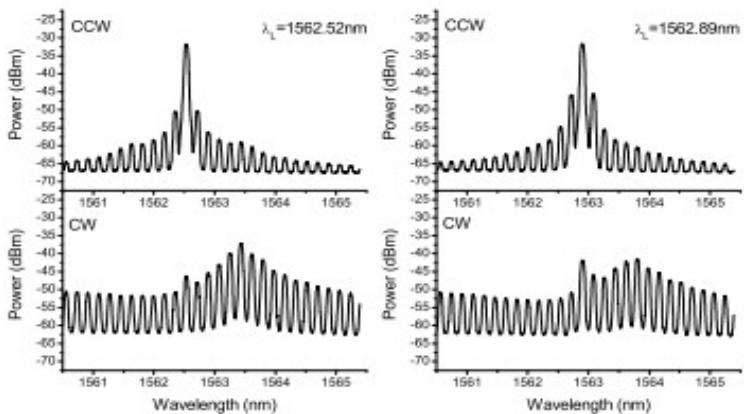
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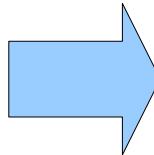
**All-optical higher order logics**

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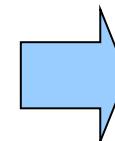


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**All-optical higher order logics**

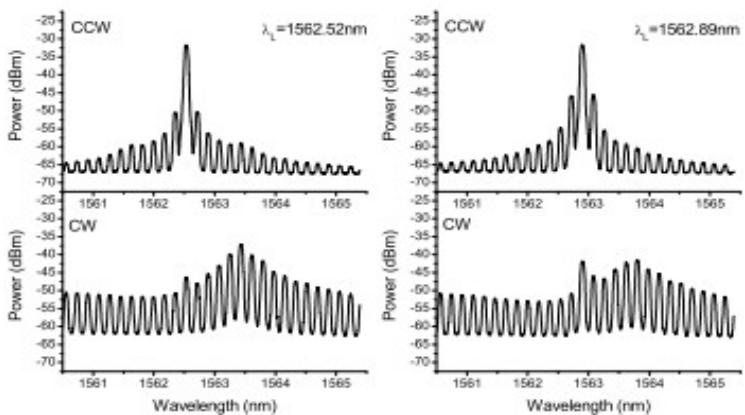
- Existing Models: Rate Equations-Like (ODEs)  
Spatial dependence simplified



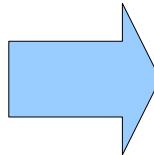
**Modal couplings??**

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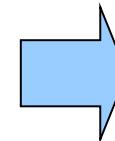


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**All-optical higher order logics**

- Existing Models: Rate Equations-Like (ODEs)  
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**Modal couplings??**

- Comprehensive theory → Taking into account spatial effects / Modal couplings
- Generality of the TWM : Description of different types of lasers.  
(PDEs) Multimode behavior arises naturally in a TWM description.

## II. The model

Dimensionless TW Equations  
for the SVA in a Semi-classical approach:

$$\pm \frac{\partial A_{\pm}}{\partial s} + \frac{\partial A_{\pm}}{\partial \tau} = B_{\pm} - \alpha A_{\pm} \quad \text{Electric Fields}$$

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$$\frac{1}{\gamma} \frac{\partial B_{\pm}}{\partial \tau} = -(1 + i\tilde{\delta})B_{\pm} + g(D_0 A_{\pm} + D_{\pm 2} A_{\mp}) + \sqrt{\beta D_0} \xi_{\pm}(s, \tau) \quad \text{Polarization}$$

$$\begin{aligned} \frac{\partial D_0}{\partial \tau} &= \epsilon [J - D_0 + \Delta \frac{\partial^2 D_0}{\partial s^2} - (A_+ B_+^* + A_- B_-^* + A_+^* B_+ + A_-^* B_-)] \\ \frac{\partial D_{\pm 2}}{\partial \tau} &= -\eta D_{\pm 2} - \epsilon (A_{\pm} B_{\mp}^* + A_{\mp}^* B_{\pm}) \end{aligned} \quad \left. \right\} \text{Carriers}$$

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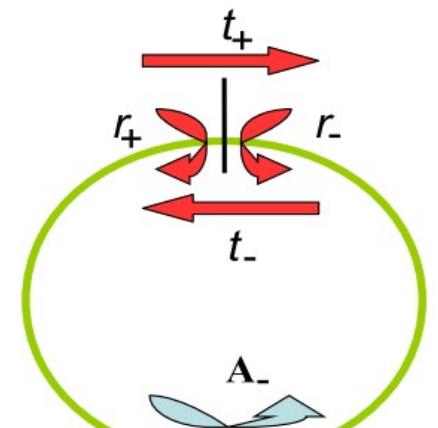
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Boundary Conditions:

$$A_+(0, \tau) = t_+ A_+(1, \tau) + r_- A_-(0, \tau)$$

$$A_-(1, \tau) = t_- A_-(0, \tau) + r_+ A_+(1, \tau)$$

FP :  $t_{\pm} = 0$   
Ideal Ring:  $r_{\pm} = 0$



## II. The model

Solving PDEs numerically:

Fleck, Phys. Rev. B **1**, 84 (1970).

Tests for the numerical algorithm:

Analytical Results (Unidirectional or UFL)

Zeghlache et al. Phys. Rev. A **37**, 470 (1988).

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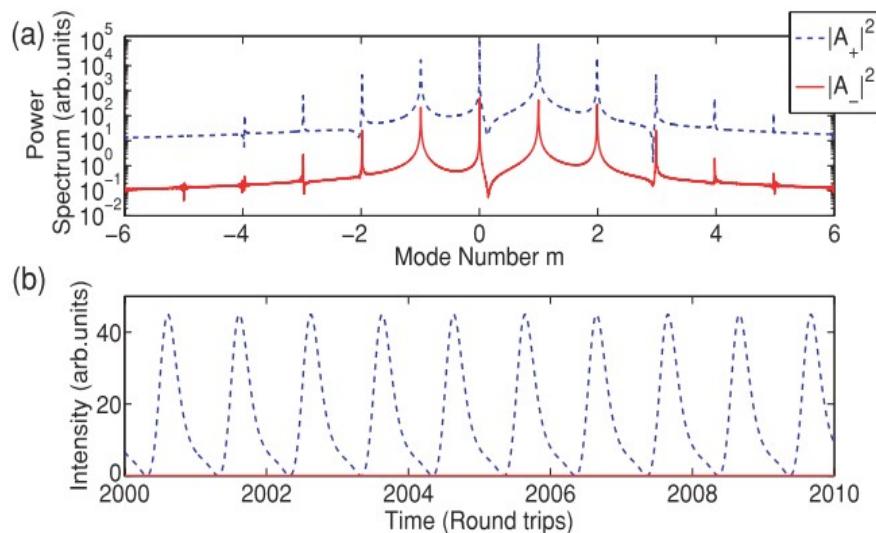
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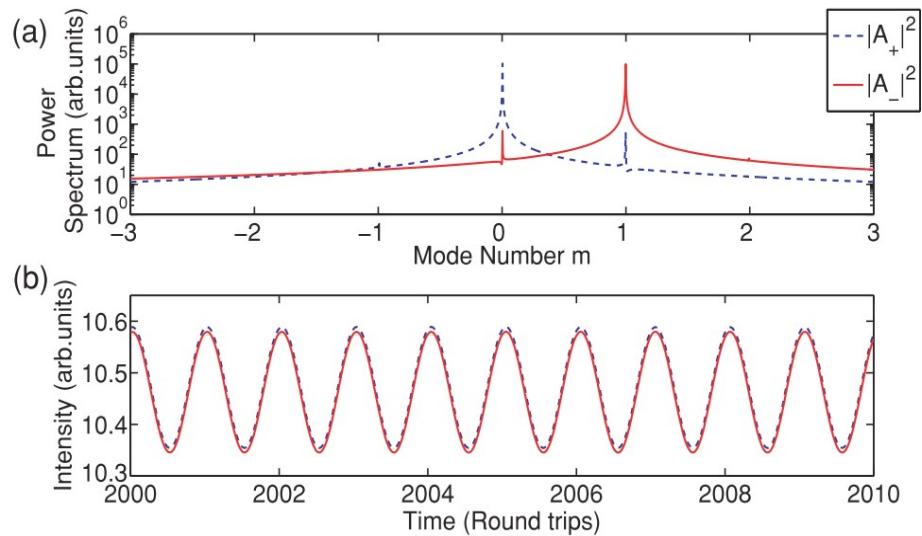
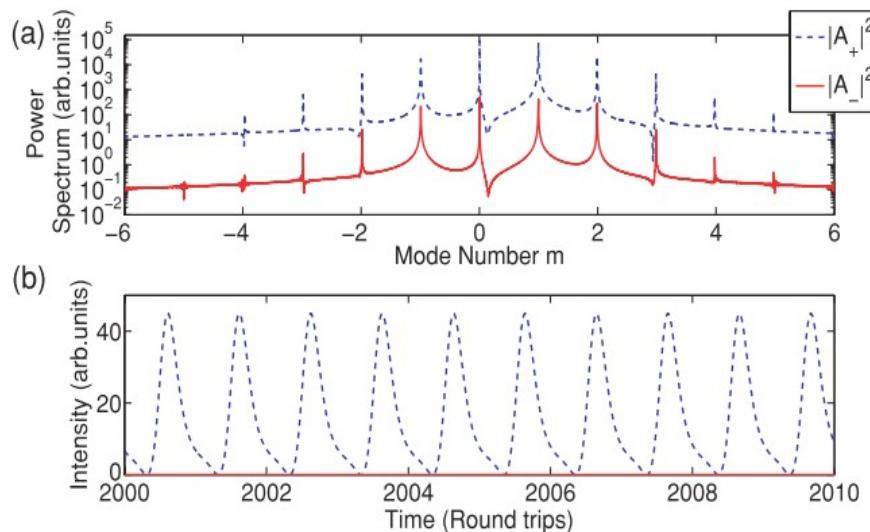
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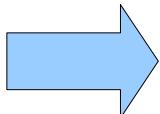
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### III. Longitudinal modal multistability in lasers

Ascertaining  
multistability



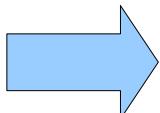
Monochromatic solutions  
Eigenvalue problem



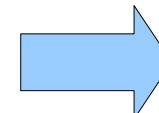
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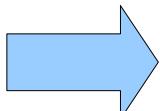
- Monochromatic Solutions via a low dimensional shooting method.



Discretized representation of the modal profile.

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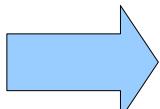


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- Monochromatic Solutions via a low dimensional shooting method.
  - Discretized representation of the modal profile.
- Eigenvalue Problem:
  - Hyperbolic PDE: discrete representation of the gradient
    - Large error in the computed eigenvalues.

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- Monochromatic Solutions via a low dimensional shooting method.  
→ Discretized representation of the modal profile.

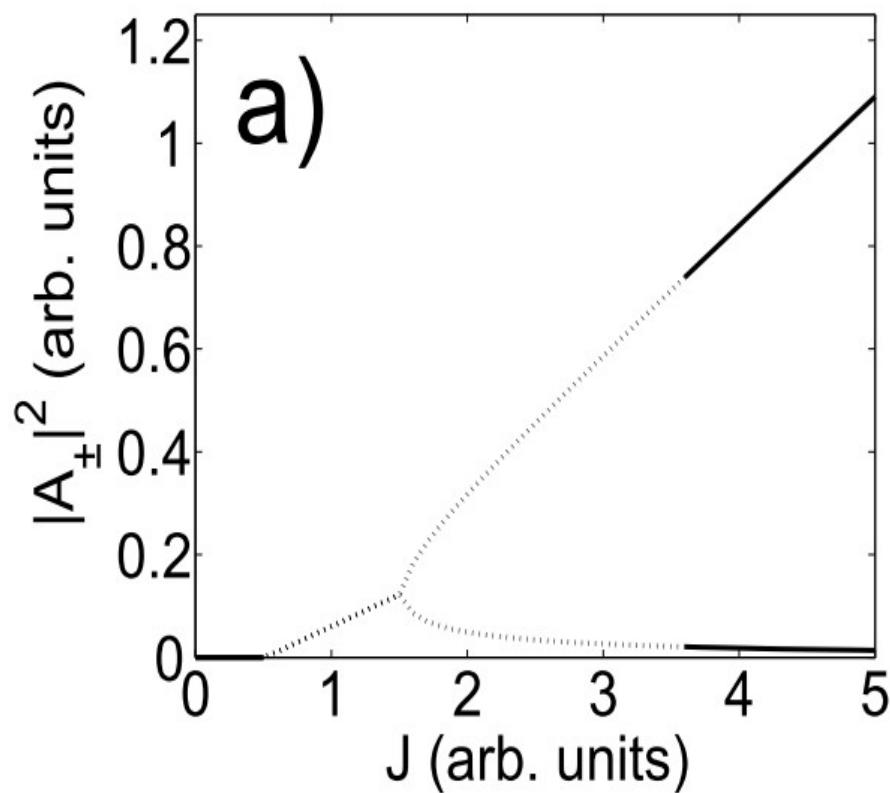
- Eigenvalue Problem:
  - Hyperbolic PDE: discrete representation of the gradient  
→ Large error in the computed eigenvalues.
  - Linearized evolution operator → Floquet multipliers



- This approach is quite general: can be used in other dynamical systems with PDEs.

### III. Longitudinal modal multistability in lasers

Bidirectional Ring laser



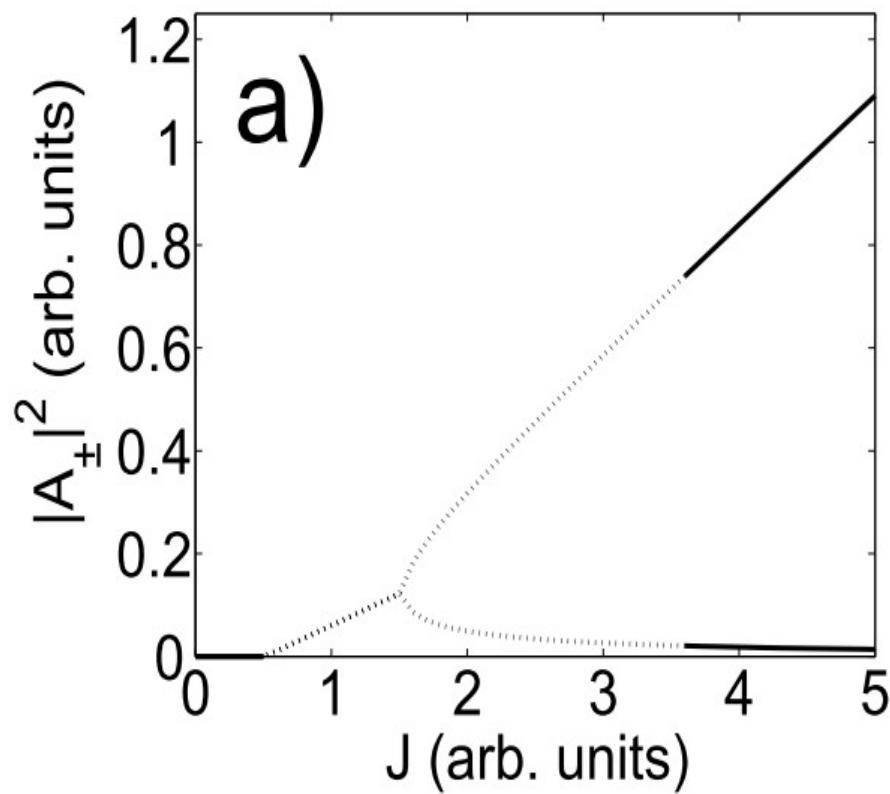
LSA for mode  $m = 2$

$g = 4$   
 $t_{\pm} = 0.98$   
 $r_{\pm} = 0.01$   
 $\varepsilon = 0.05$   
 $\eta = 10$   
 $\gamma = 250$   
 $\Delta = 0$   
 $\alpha = 2.03$

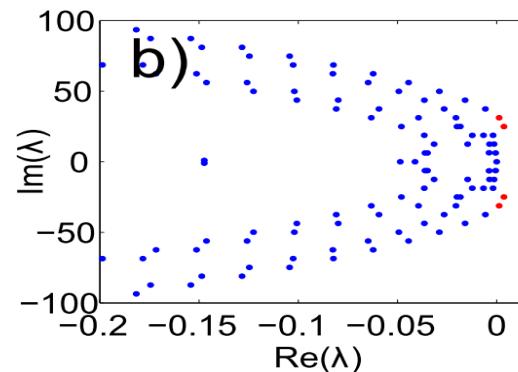
Typical parameters  
for  
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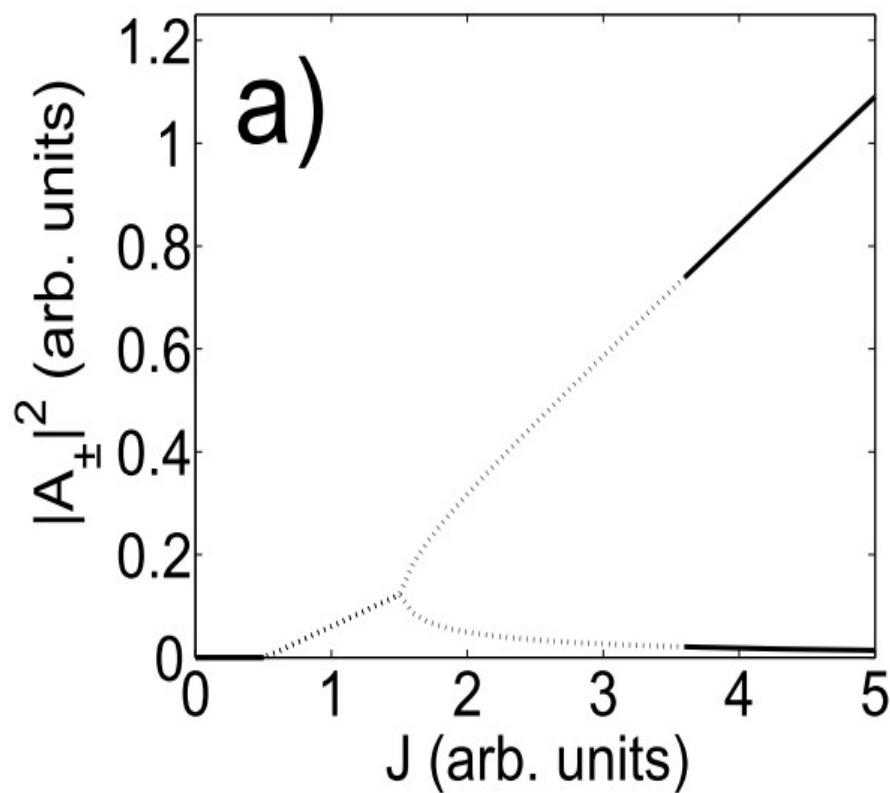


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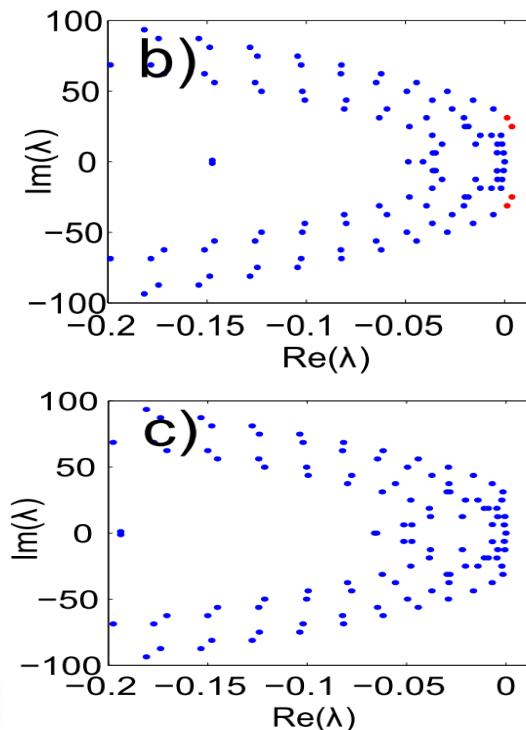
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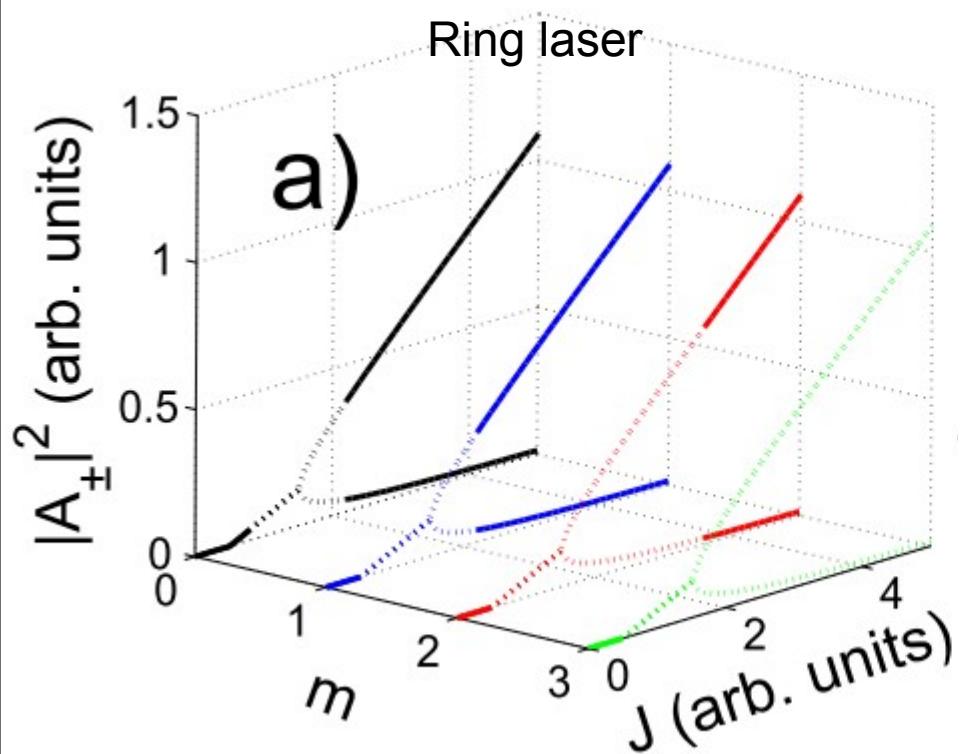


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### III. Longitudinal modal multistability in lasers

Uniform Field Limit (UFL)



### III. Longitudinal modal multistability in lasers

Fair comparison between Ring and FP lasers:

Both should work with the same degree of gain saturation, hence the pump density and the threshold pump density should be the same in both cases.

{  
Ring: single pass on the cavity  
FP: roundtrip

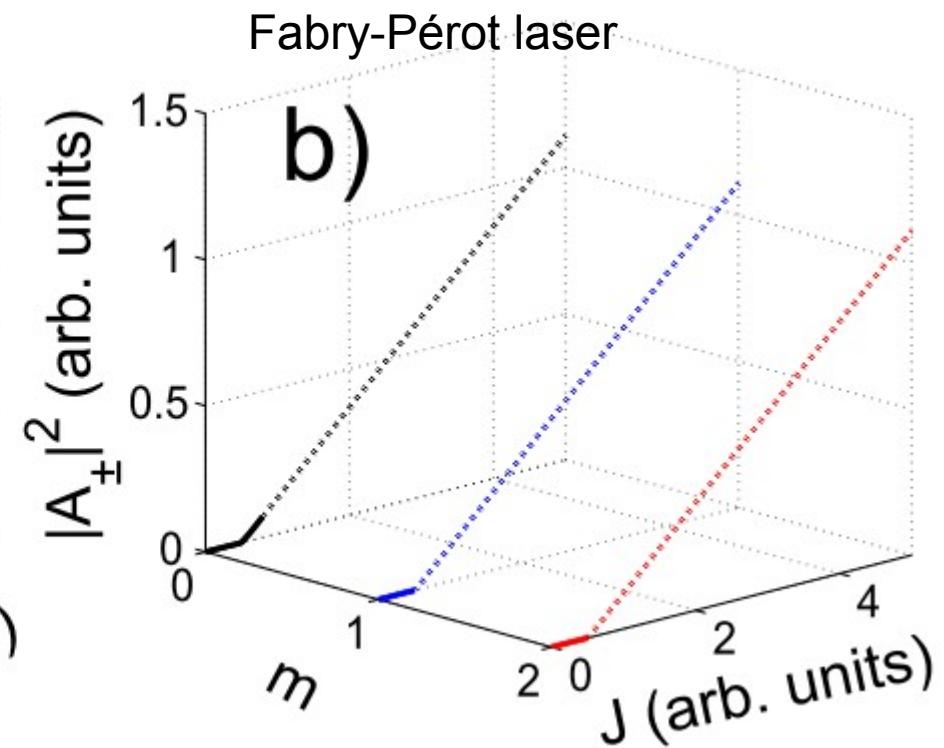
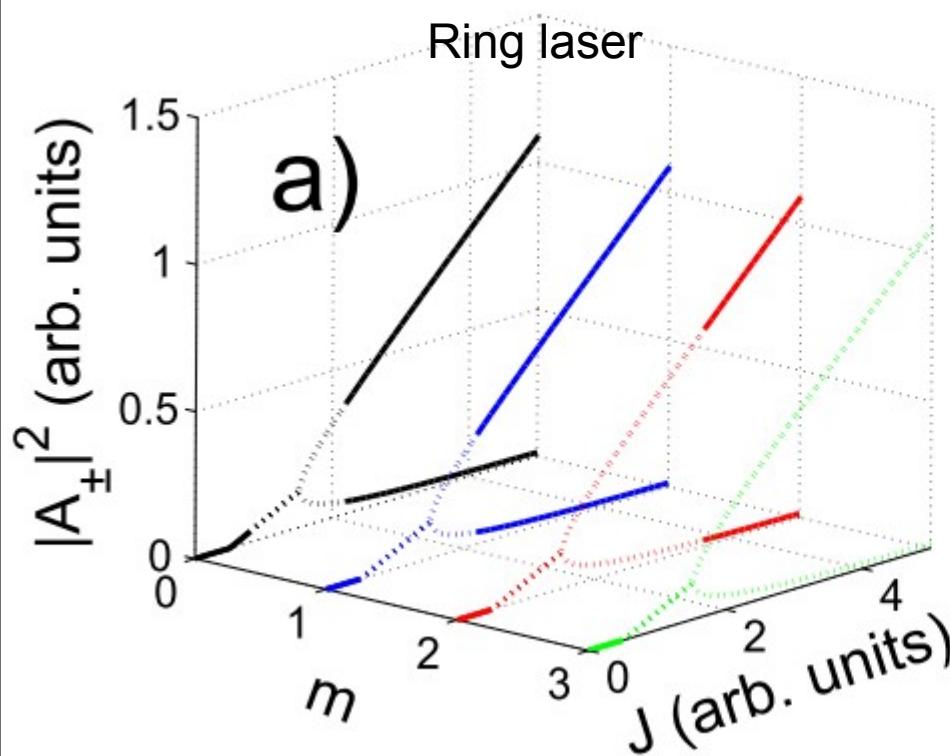


$$L_{\text{Ring}} = 2 L_{\text{FP}}$$

A large blue arrow pointing from left to right, indicating a comparison or consequence.
$$\left\{ \begin{array}{l} g_{\text{Ring}} = 2 g_{\text{FP}} \\ \gamma_{\text{Ring}} = 2 \gamma_{\text{FP}} \\ \varepsilon_{\text{Ring}} = 2 \varepsilon_{\text{FP}} \\ \eta_{\text{Ring}} = 2 \eta_{\text{FP}} \end{array} \right.$$

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Uniform Field Limit (UFL)

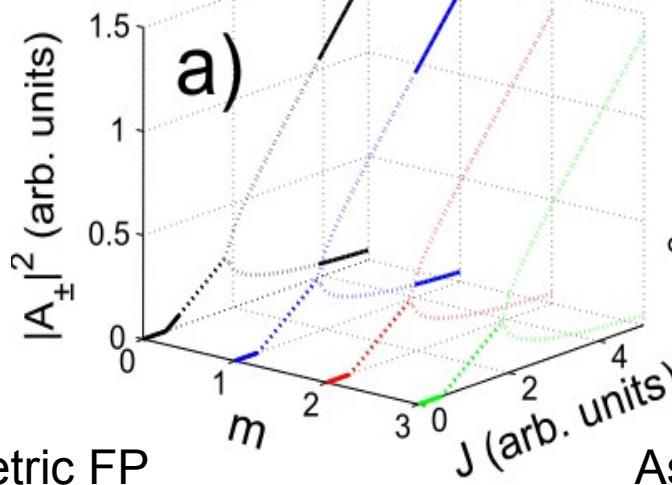


$$t_{\pm} = 0, r_{\pm} = 0.99, \alpha = 1.01$$

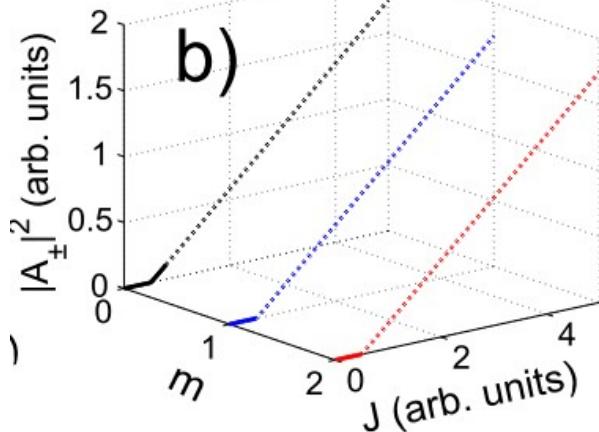
### III. Longitudinal modal multistability in lasers

High losses lasers

Ring laser



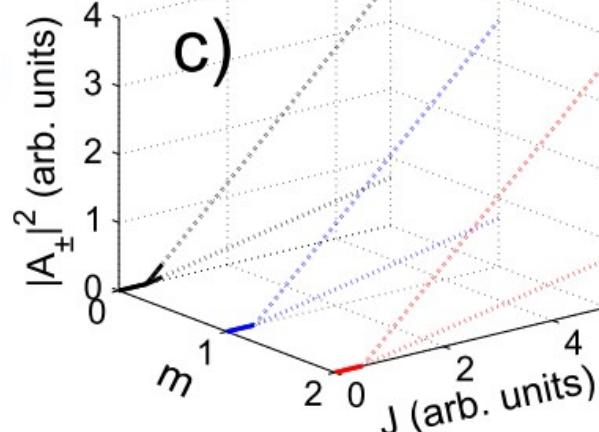
Symmetric FP



$$\begin{aligned} t_{\pm} &= 0 \\ r_{\pm} &= 0.6 \\ \alpha &= 0.51 \end{aligned}$$

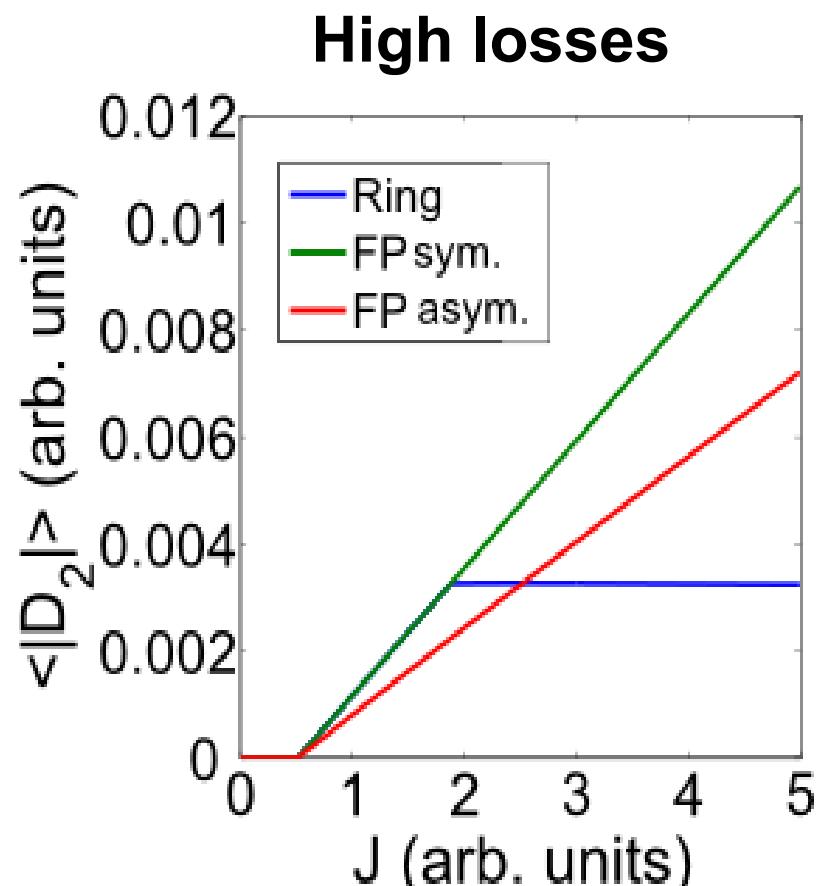
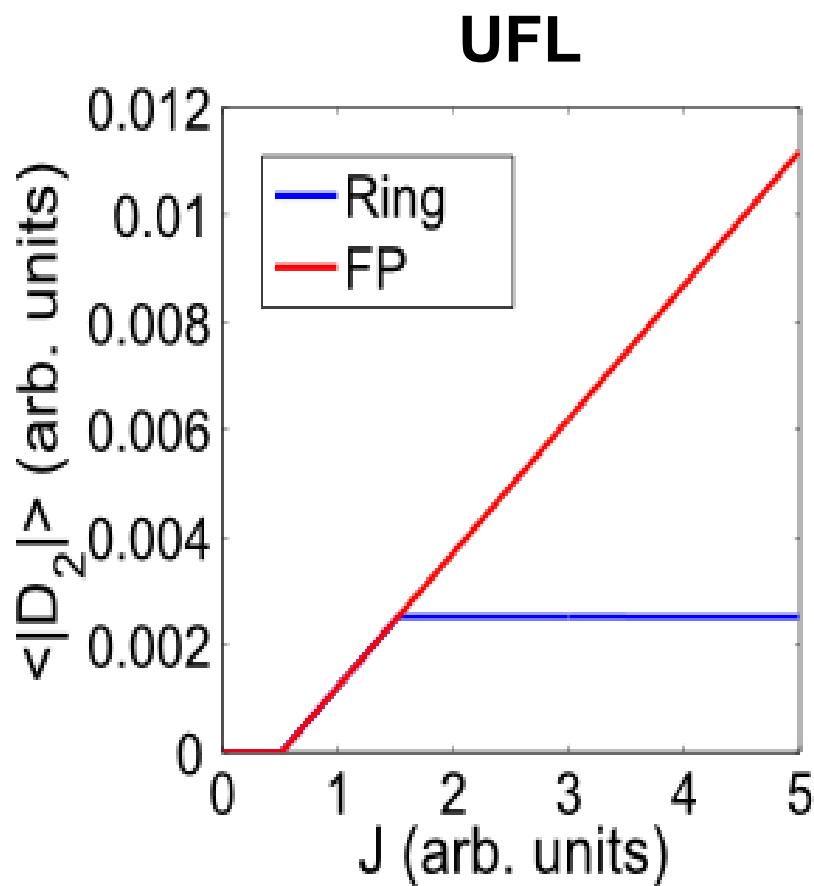
$$\begin{aligned} g &= 4 & \Delta &= 0 \\ t_{\pm} &= 0.6 & \alpha &= 1.55 \\ r_{\pm} &= 0.01 & \varepsilon &= 0.05 \\ \varepsilon &= 0.05 & \eta &= 10 \\ \eta &= 10 & \gamma &= 250 \\ \gamma &= 250 & \delta &= 0 \end{aligned}$$

Asymmetric FP

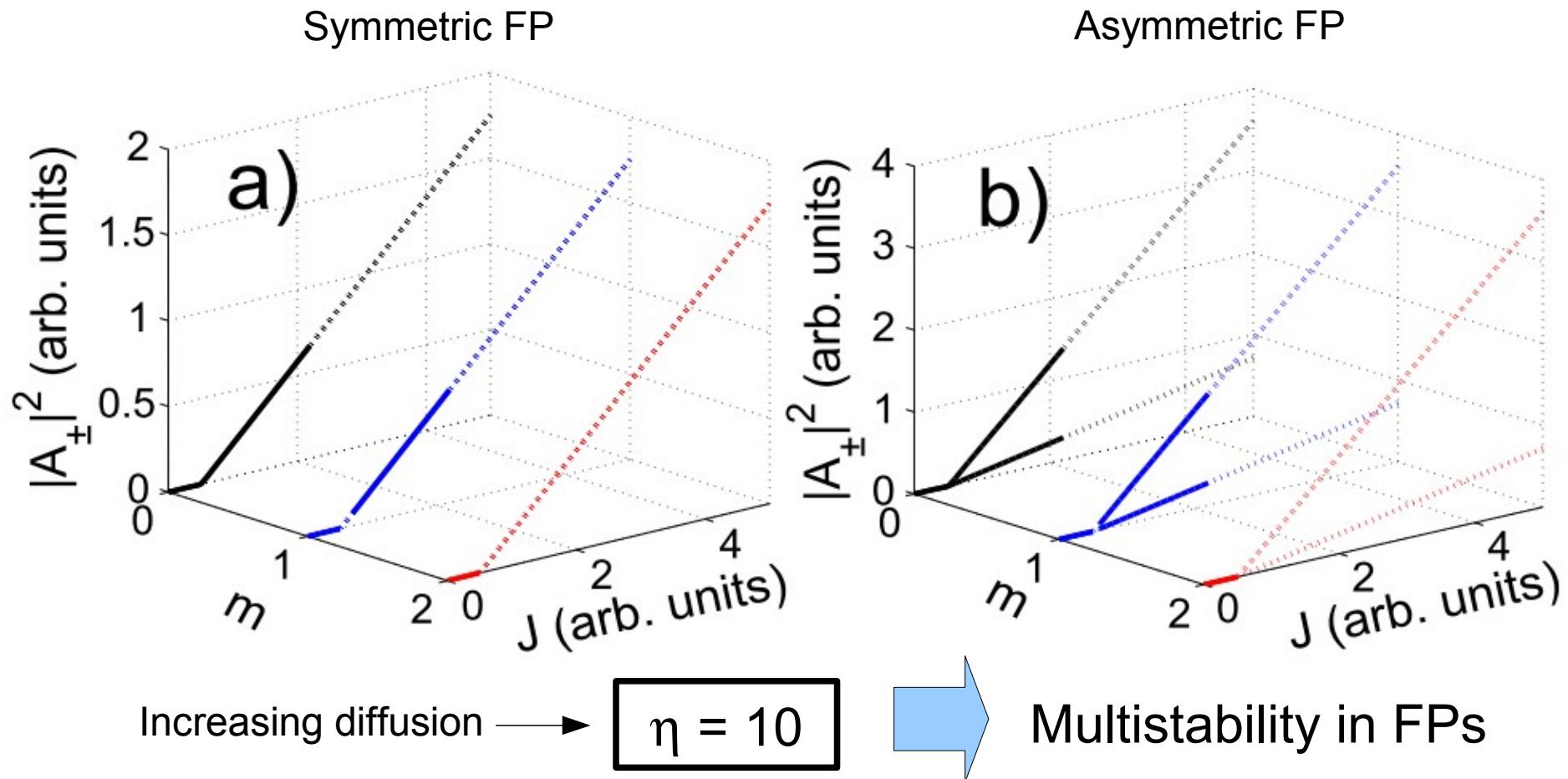


$$\begin{aligned} t_{\pm} &= 0 \\ r_{\pm} &= 0.99 \\ r_- &= 0.2 \\ \alpha &= 0.21 \end{aligned}$$

### III. Longitudinal modal multistability in lasers



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## IV. Conclusions

- We theoretically discuss the impact of the cavity configuration on the possible longitudinal mode multistability in homogeneously broadened lasers based on a general form of a Travelling Wave Model.
- The LSA performed can be exported to other dynamical systems involving PDEs.
- Multistability is more easily reached in Ring lasers than in FP lasers and is due to the different amounts of Spatial Hole Burning in each configuration.
  - In a high quality Ring with low reflectivities, the grating terms are small, then self-saturation is smaller than cross-saturation, and multistability appears.
  - In a FP configuration the grating effects are usually important, then self-saturation is bigger than cross-saturation and multistability is not allowed. This grating effect can be reduced by increasing diffusion.

# Thank you for your attention!

For details:

Pérez-Serrano et al. Phys. Rev. A **81**, 043817 (2010).

Pérez-Serrano et al. Opt. Express **19**, 3284 (2011).

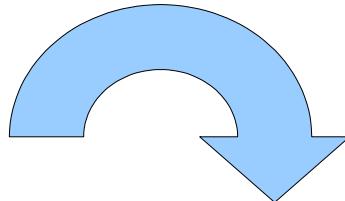
Financial Support:



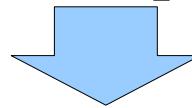
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# \* Numerical methodology I

Monochromatic solutions solved numerically via a multidimensional shooting method:

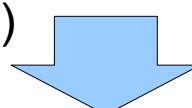


A guess is proposed for the modal frequency  $\omega_0$  and the fields at  $s = 0$ ,  $A_{\pm}(0)$

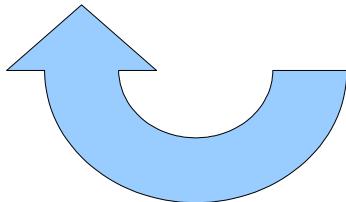


Numerical integration in space ( step =  $1/N$  )

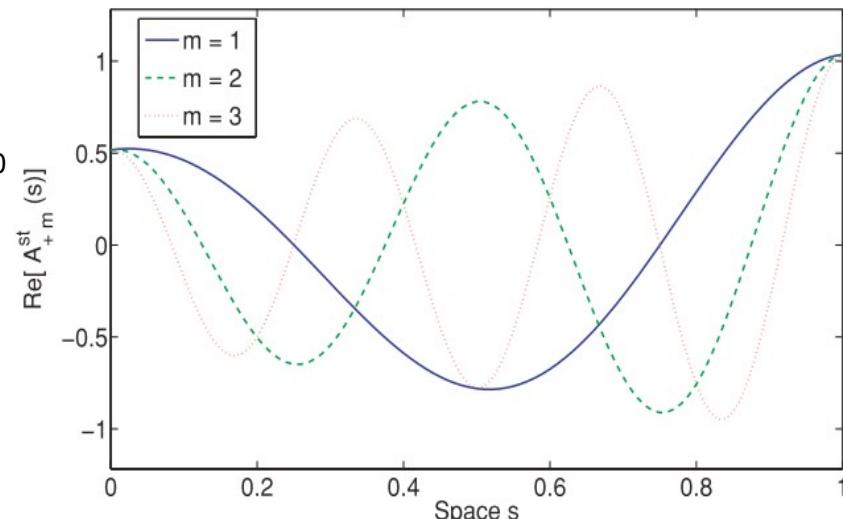
One obtains  $A_{\pm}(1)$



Verifying the boundary conditions a low dimensional Newton-Raphson computes a new guess for  $A_{\pm}(0)$  and  $\omega_0$ . The process is repeated until convergence.



Discretized modal profile



# \* Numerical methodology II (LSA)

Being  $\mathbf{V}^*$  a monochromatic solution, we go to the reference frame  $\omega$ .

From the TWM (PDEs) we construct the evolution operator  $\mathbf{U}(h, \mathbf{V}_n)$ .

We use the temporal map  $\mathbf{V}_{n+1} = \mathbf{U}(h, \mathbf{V}_n)$  to advance the state vector  $\mathbf{V}$  a time step  $h$ , while verifying the Courant condition and cancelling numerical dissipation, then  $\mathbf{V}_{n+1}^* = \mathbf{U}(h, \mathbf{V}_n^*) = \mathbf{V}_n^*$

We consider all possible perturbations of  $\mathbf{V} = \mathbf{V}^* + \delta\mathbf{V}$  finding the matrix  $\mathbf{M} = \partial\mathbf{U}/\partial\mathbf{V}$   
Where  $\mathbf{M}$  is the linearized evolution operator.

We compute 11xN Floquet multipliers  $\mathbf{z}_i$  of  $\mathbf{M}$

$$\lambda_i = h^{-1} \ln z_i$$

\* e.g. N = 256, standard PC using C++ routine based on Octave

Monochromatic solution → 1 s

Generating  $\mathbf{M}$  → 10 s

Diagonalizing with QR decomposition → 60 s