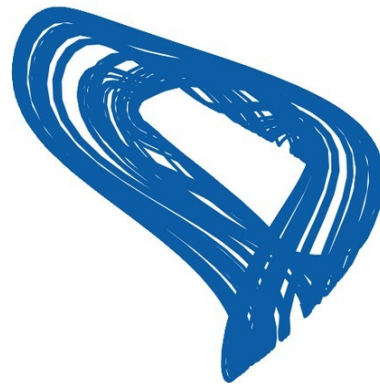


Inferring Untrained Dynamics of Complex Systems using Adapted Recurrent Neural Networks

Mirko Goldmann, Claudio R. Mirasso, Ingo Fischer, and **Miguel C. Soriano**



Dynamics Days Europe 2022
25 August 2022

- IFISC: Institute for Cross-Disciplinary Physics and Complex Systems in Mallorca.
- Joint research Institute of the University of the Balearic Islands (UIB) and the Spanish National Research Council (CSIC) created in 2007.



Complex Dynamics @ IFISC

Apostolos Argyris

Irene Estébanez

Moritz Pflüger

Claudio R. Mirasso

Mirko Goldmann

Lucas Talandier

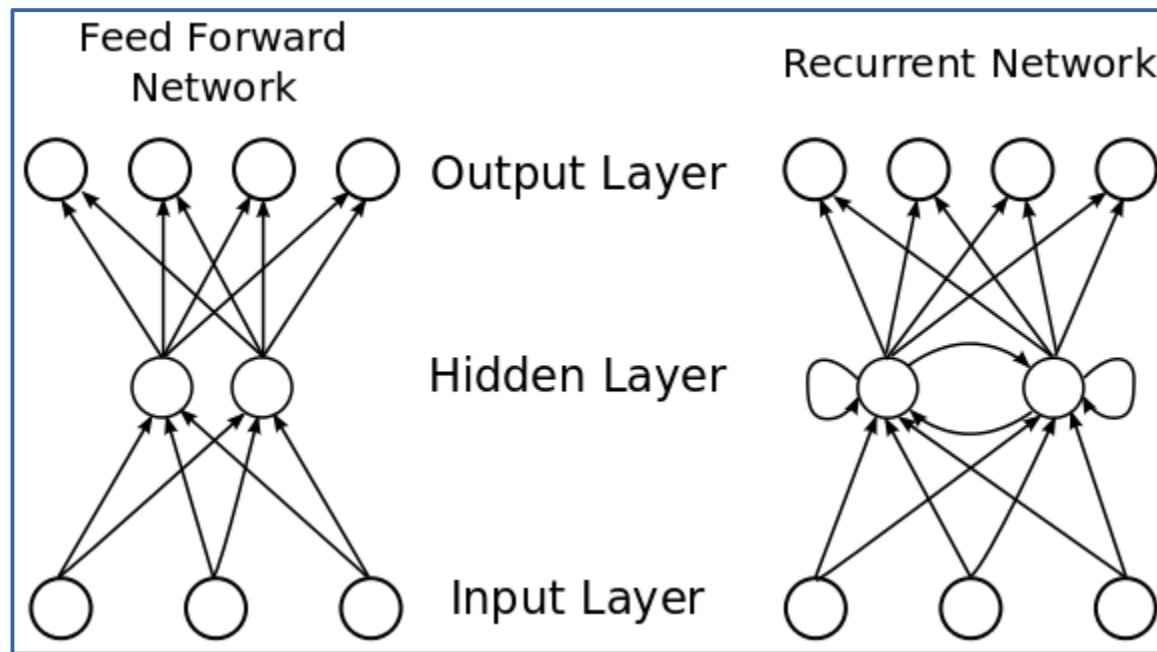
Silvia Ortín

Ingo Fischer

Jyoti P. Deka



Machine Learning meets Dynamical Systems

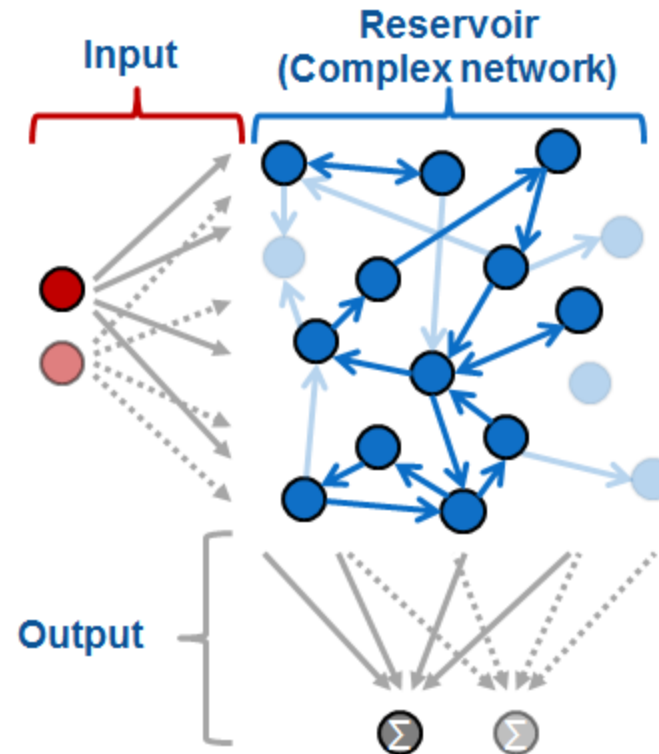


Feed forward Neural Network can approximate any continuous function (≥ 1 hidden layers + non-linear activations)

Recurrent Neural Networks can approximate **dynamical systems**



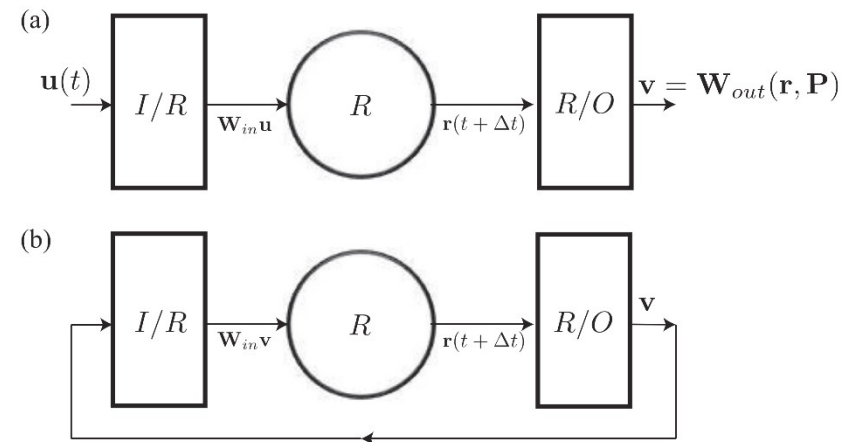
- **Neuro-inspired concept**
 - Consider a “black-box (reservoir)” complex recurrent network
 - The input nodes connected randomly to reservoir nodes
 - Output weights are trained
- Generate **nonlinear transient responses** to input
- Mapping to a **high-dimensional space**



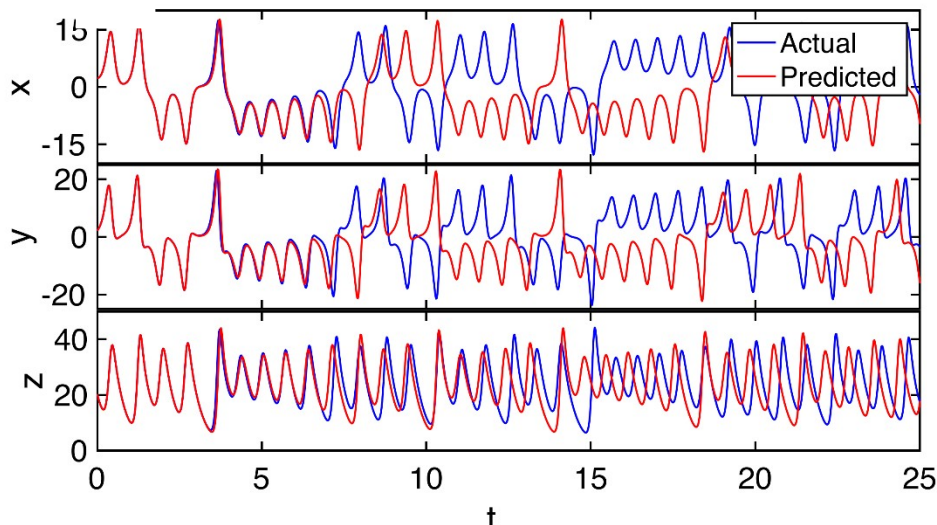
Can emulate chaotic dynamical systems!

Lorenz model

$$\begin{aligned} \dot{x} &= 10(y - x), \\ \dot{y} &= x(28 - z) - y, \\ \dot{z} &= xy - 8z/3. \end{aligned}$$



R → Echo State Network (popular variant of RC)



	Actual Lorenz system	R1 system
Λ_1	0.91	0.90
Λ_2	0.00	0.00
Λ_3	-14.6	-10.5

J. Pathak, Z. Lu, B. R. Hunt, M. Girvan, and E. Ott. "Using machine learning to replicate chaotic attractors and calculate Lyapunov exponents from data." *Chaos* 27, 121102 (2017).

Infer unseen/untrained dynamics of systems by learning from a single example?

- physical models are parametrized \rightarrow changing parameter leads to new behavior/dynamics

$$\dot{x}(t) = F(x(t), c)$$

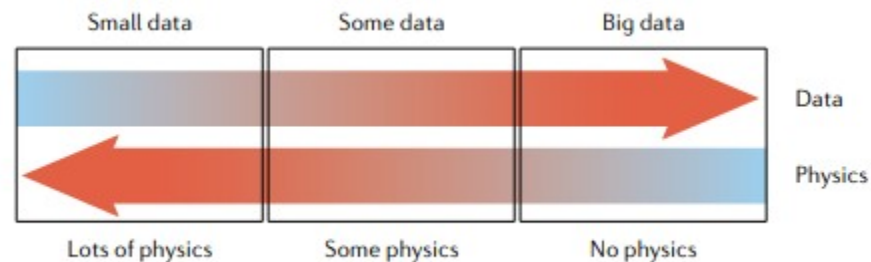
- ML: statistical learning without being aware of parametrization of the physical model

- Physics-informed machine learning**

- Using physical knowledge to constrain the learning

- biases on:

- training data
- loss function
- network topology



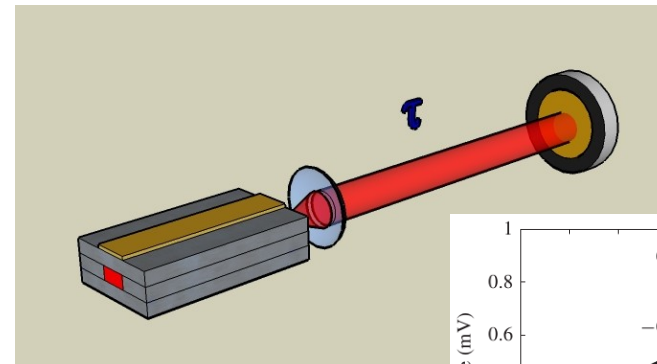
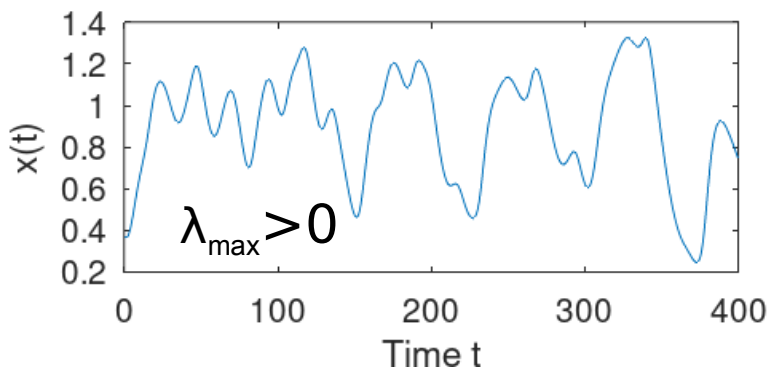
G. E. Karniadakis et al., "Physics-informed machine learning." Nature Reviews Physics 3, 422-440 (2021).

Delay Systems

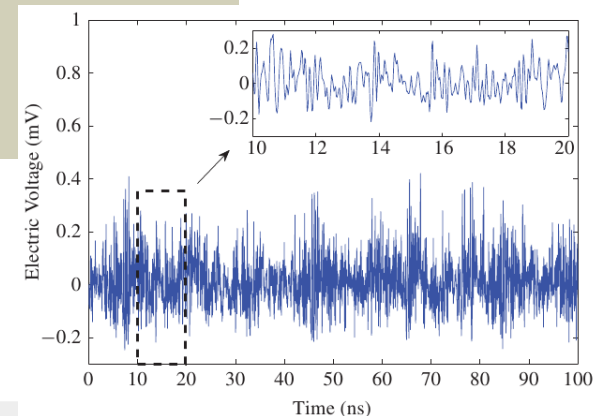
$$\dot{x}(t) = F(x(t), x(t - \tau); p)$$

- delays appear where signal propagation is finite
 - neuroscience, photonics, epidemiologic models and control problems
- rely on a continuous history function $h \in [-\tau, 0]$
 - infinite dimensional
- for long delays these systems can become chaotic

Mackey-Glass system



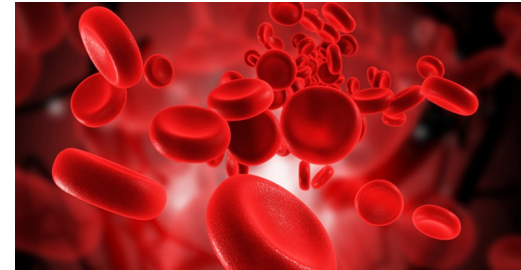
SL with feedback



Time lag can be substantial in physiological systems

Example: following a loss of **blood cells**, it can take many days before new blood cells can be produced (activation, differentiation, and proliferation of the blood stem cells)

$$\frac{dx}{dt} = \beta \frac{x_\tau}{1 + x_\tau^n} - \gamma x, \quad \gamma, \beta, n > 0,$$



Mackey-Glass equation (for the **nonlinear production control** function)

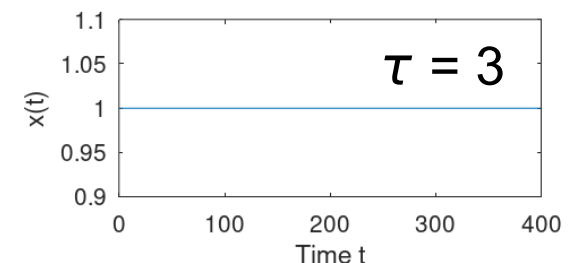
- x : concentration (assumed non-negative for all times) of circulating blood cells
- β , γ and n : constants controlling the production of these cells
- x_τ , $x(t-\tau)$

For some intermediate values of x_τ the production rate would be adequate

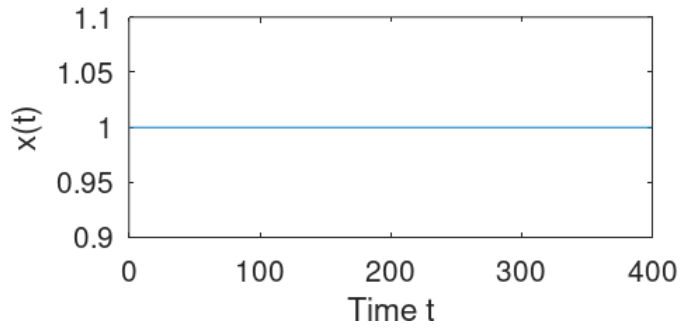
If $0 < x_\tau \ll 1$ individual would be sick and unable to generate enough blood cells

If $1 \ll x_\tau$ person would have too many blood cells so that the production rate would once again be low

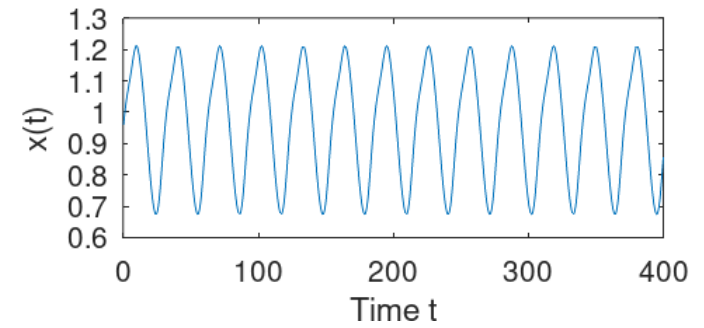
$$\beta=0.2, \gamma=0.1 \text{ and } n=10$$



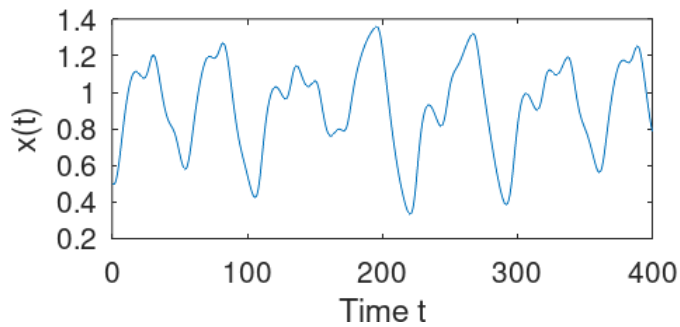
$\tau = 3$



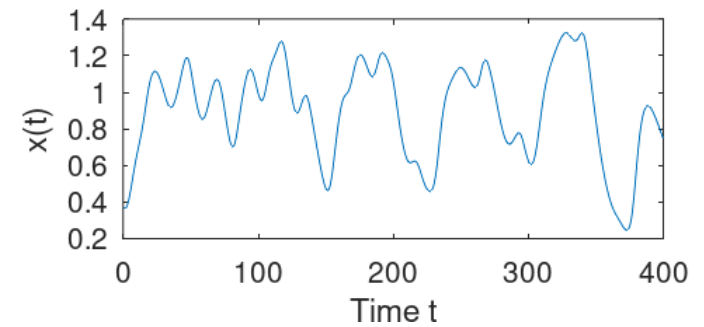
$\tau = 10$



$\tau = 20$

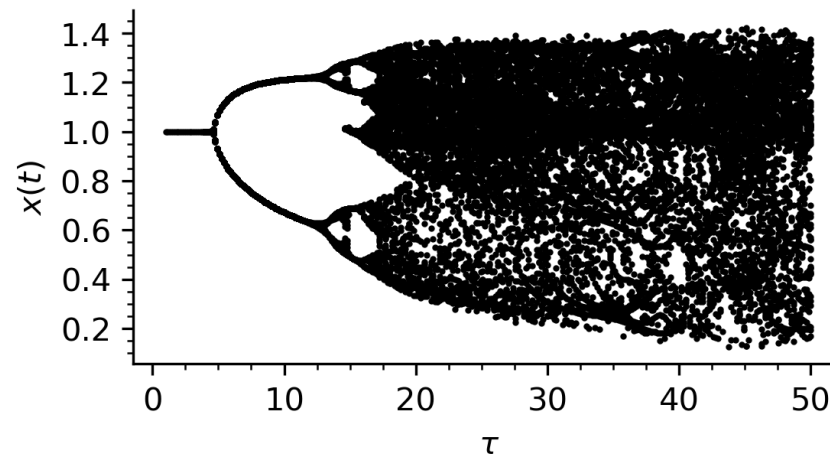


$\tau = 30$

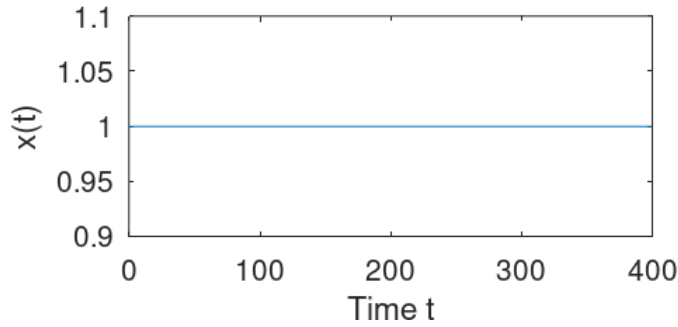


$$\frac{dx}{dt} = \beta \frac{x_\tau}{1 + x_\tau^n} - \gamma x,$$

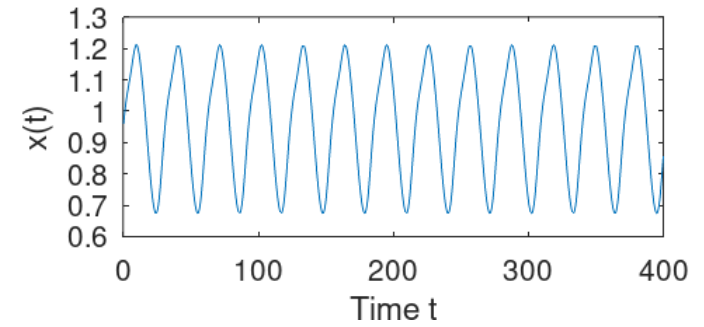
$\beta=0.2, \gamma=0.1$ and $n=10$



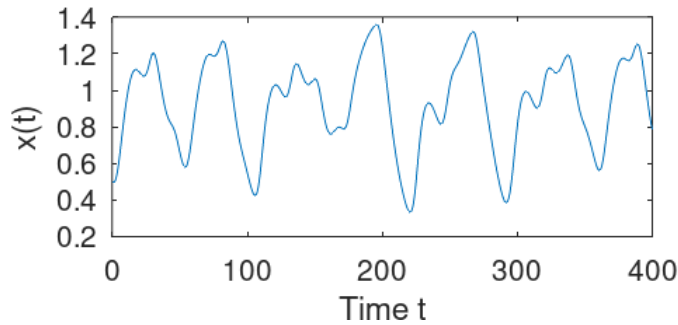
$\tau = 3$



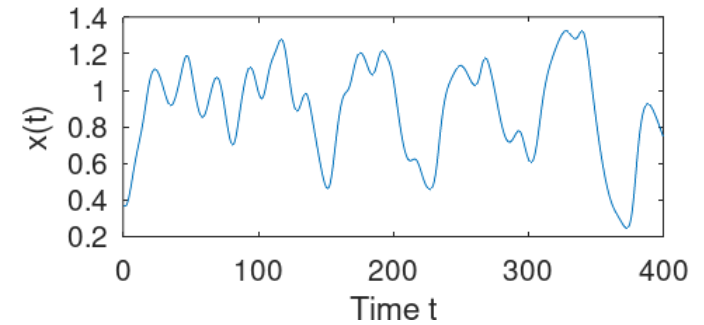
$\tau = 10$



$\tau = 20$

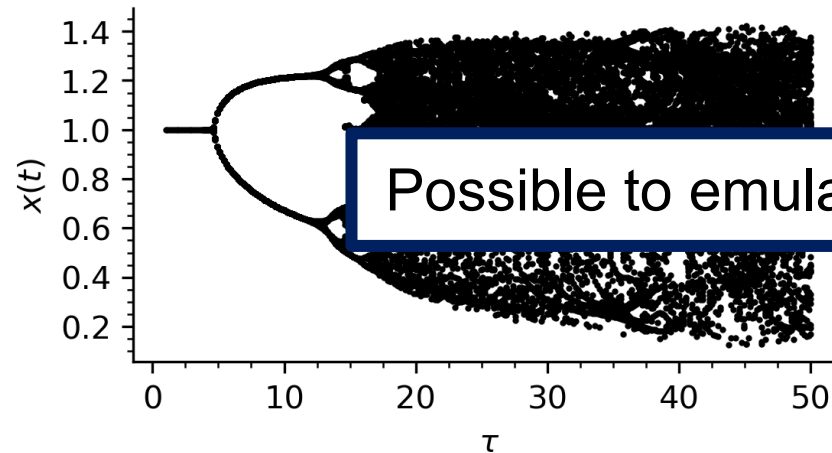


$\tau = 30$



$$\frac{dx}{dt} = \beta \frac{x_\tau}{1 + x_\tau^n} - \gamma x,$$

$\beta=0.2, \gamma=0.1$ and $n=10$

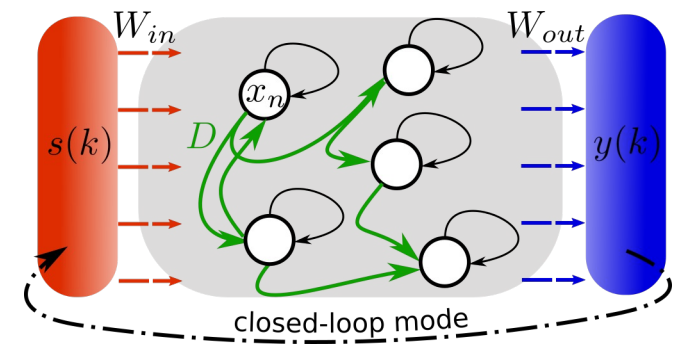


Possible to emulate with ML?

Delayed Echo State Networks

Incorporate a delay into the neural network

$$\vec{x}(n+1) = \alpha\vec{x}(n) + \beta \tanh(\mathbf{W}\vec{x}(n-D) + \gamma\mathbf{W}_{in}s(n) + \mathbf{W}_b)$$

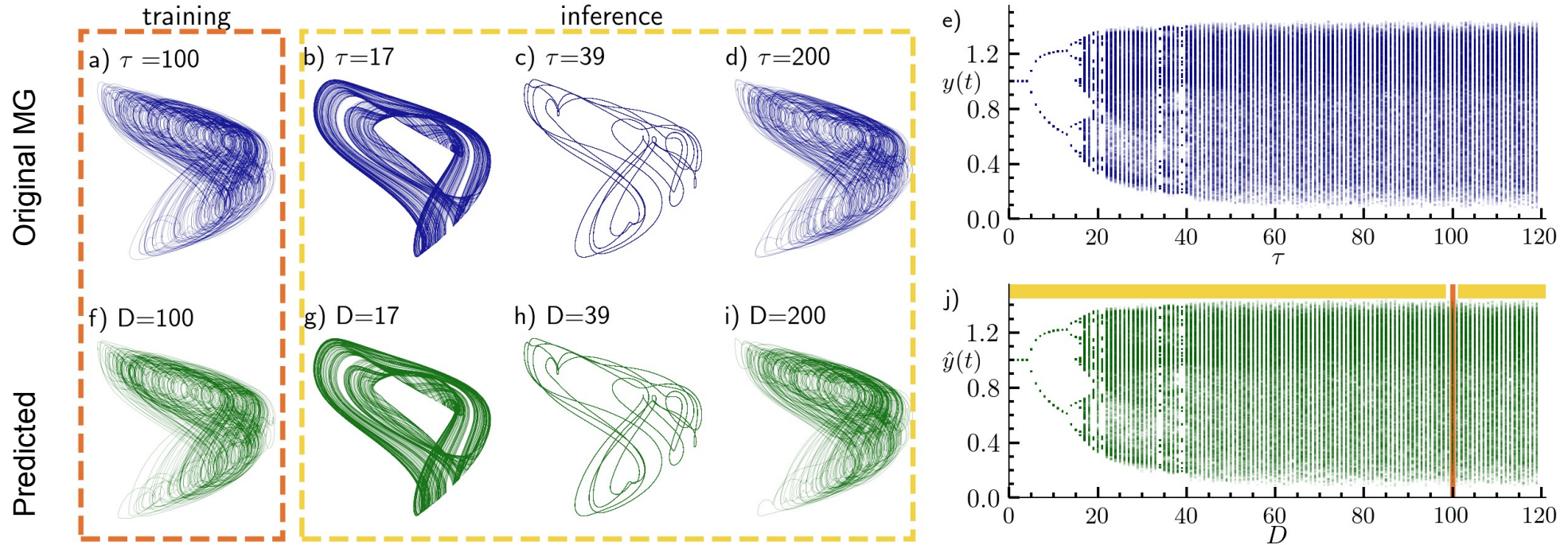


Optimal prediction performance for data of Mackey Glass system (τ) at $D=\tau$

- Optimizing hyperparameters with bayesian optimization
- Closed-loop mode: training the output layer and feeding back prediction

$$\vec{x}(n+1) = \alpha\vec{x}(n) + \beta \tanh(\mathbf{W}\vec{x}(n-D) + \gamma\mathbf{W}_{in}W_{out}x(n) + \mathbf{W}_b)$$

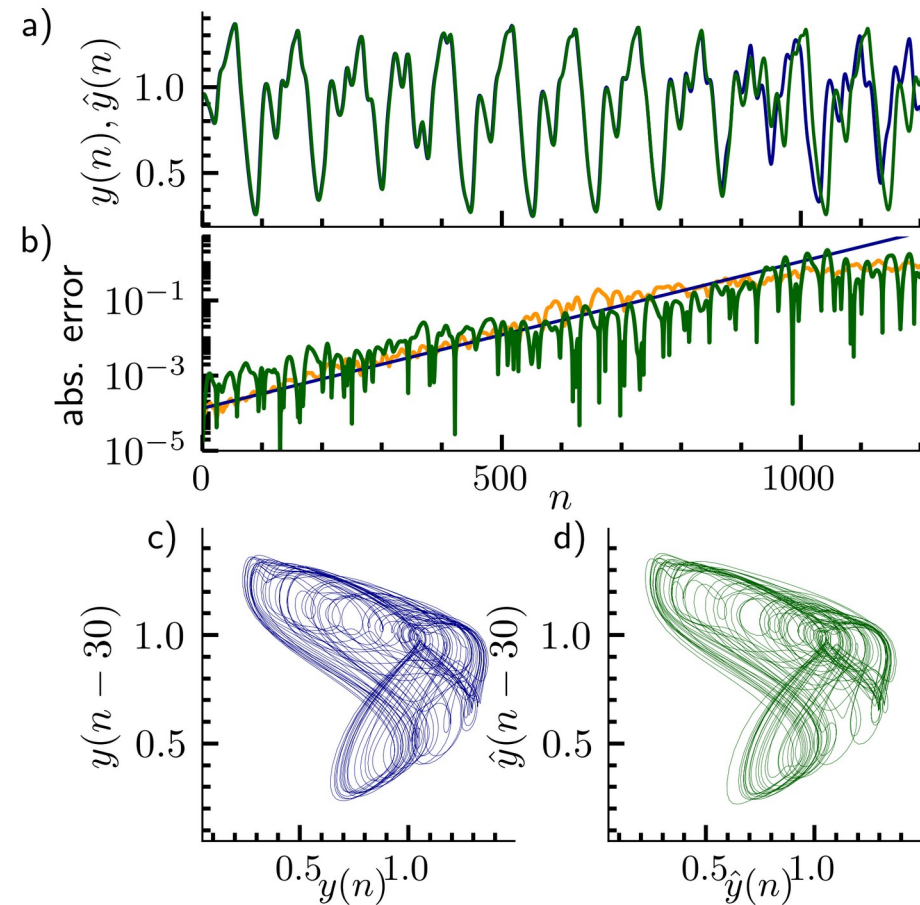
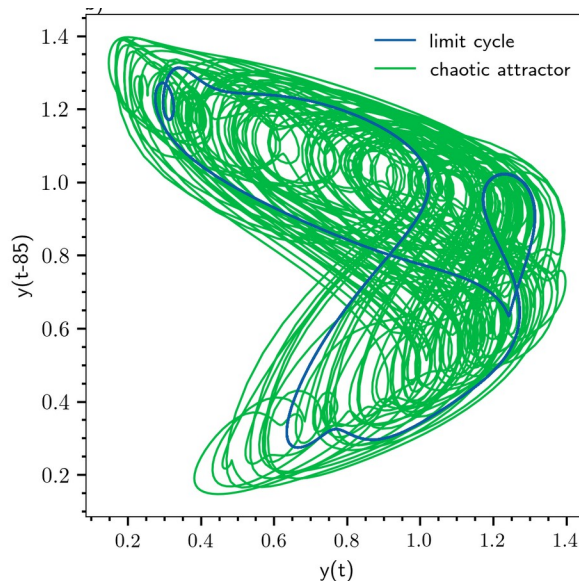
After training reconfigure network by setting delay D to untrained values
 → Inferring unseen dynamical regimes



- Training for a long delay $D, \tau = 100$
- After training scanning D
- Learning one size enables to infer the entire bifurcation diagram

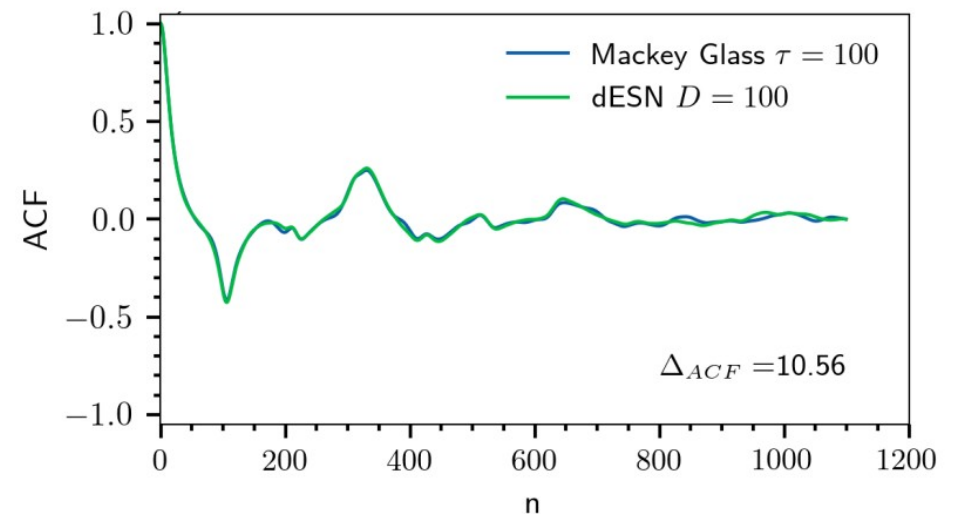
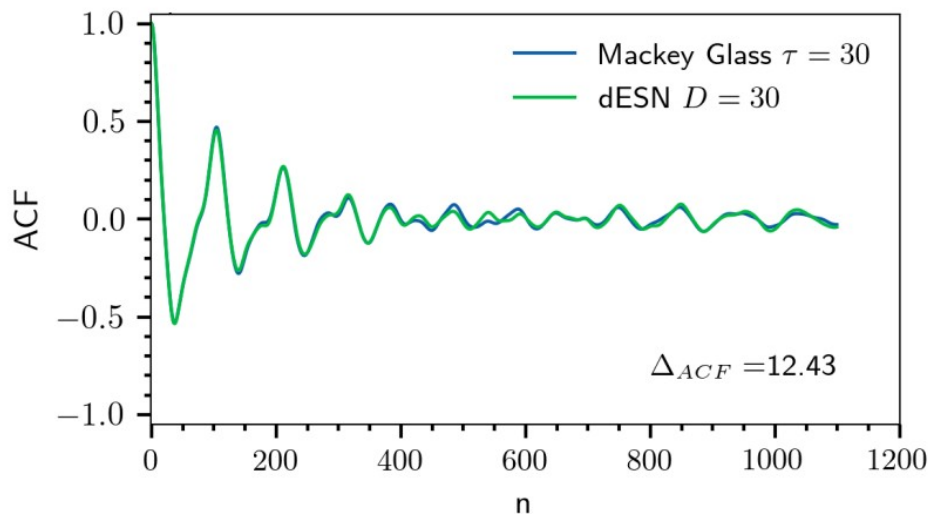
Possible to emulate with ML!

- Training at a delay of $D=100$
 - † After training: reducing the delay length to $D=30$
 - † Inference reveals unseen/untrained chaotic attractor
 - † Lyapunov exponent can be precisely derived from the reservoir
- Method even reveals multistabilities of the Mackey-Glass system



Autocorrelation function (ACF)

$$r_\tau = \frac{c_\tau}{c_0}, \quad c_\tau = \frac{1}{N} \sum_{t=1}^{N-\tau} (x_t - \langle X \rangle)(x_{t+\tau} - \langle X \rangle)$$

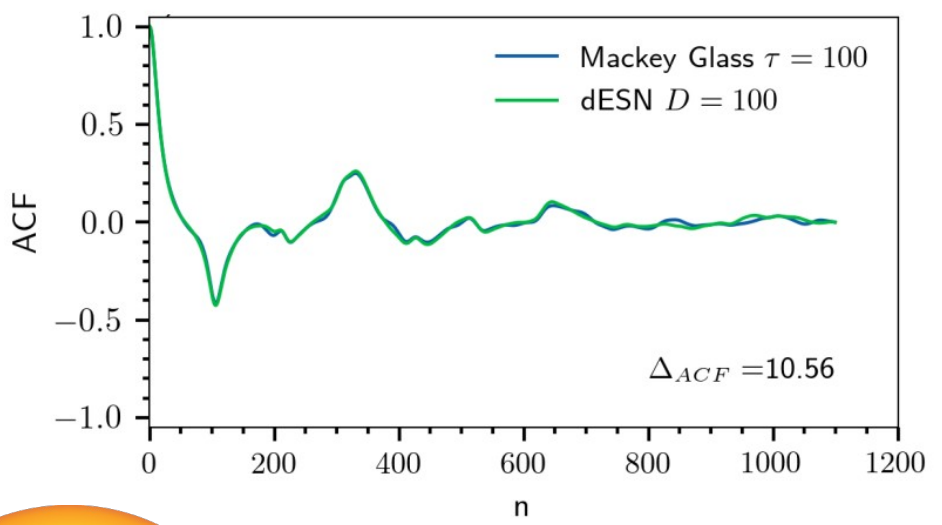
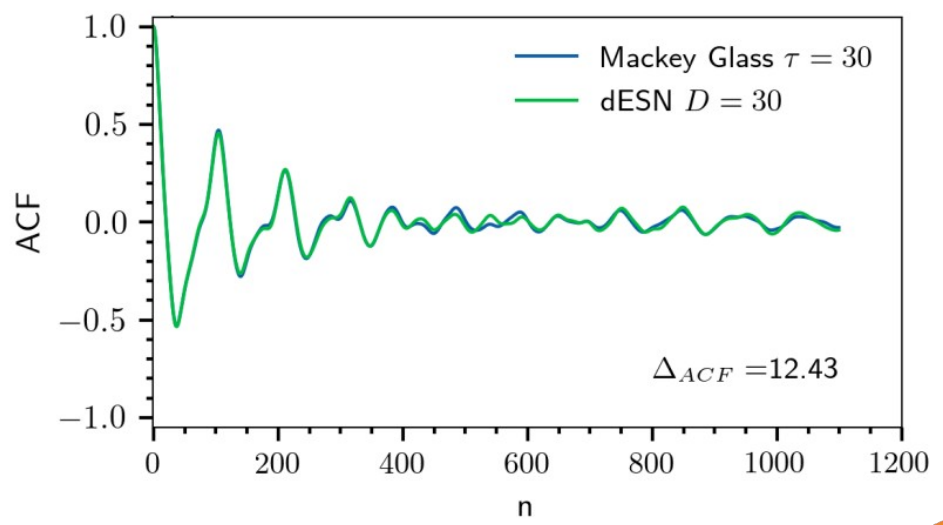


- Adapted Echo State Network reproduces the correlation properties
 - → for training example $D, \tau = 100$
 - → for unseen dynamics $D, \tau = 30$

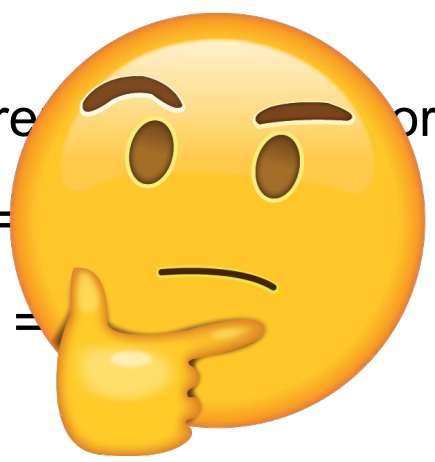
$$\Delta_{ACF} = \sum_i |ACF_{MG} - ACF_{dESN}|$$

Autocorrelation function (ACF)

$$r_\tau = \frac{c_\tau}{c_0}, \quad c_\tau = \frac{1}{N} \sum_{t=1}^{N-\tau} (x_t - \langle X \rangle)(x_{t+\tau} - \langle X \rangle)$$



- Adapted Echo State Network re... correlation properties
 - for training example $D, \tau =$
 - for unseen dynamics $D, \tau =$

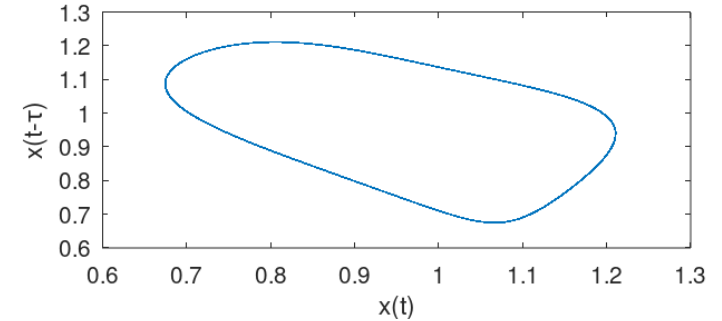
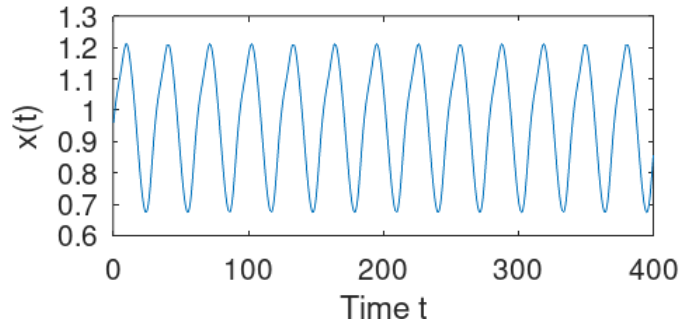


Does it always work?

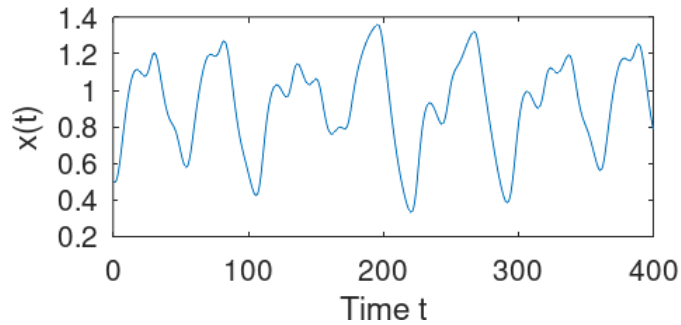
$$\frac{dx}{dt} = \beta \frac{x_\tau}{1 + x_\tau^n} - \gamma x$$

Mackey-Glass attractors: from stable to periodic and chaotic dynamics

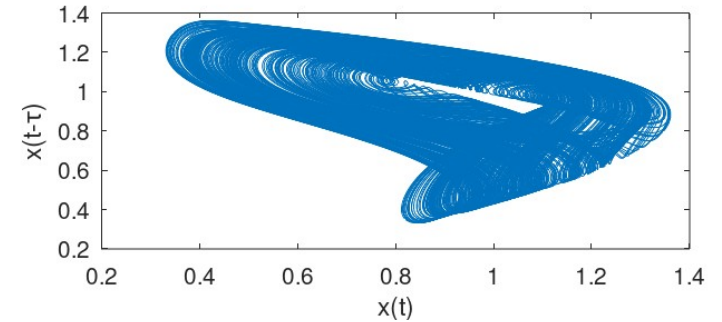
$\tau = 10$



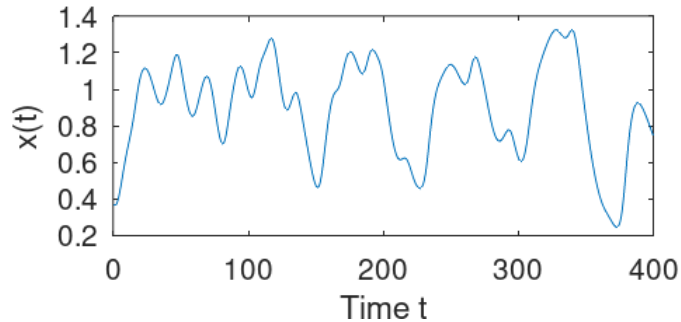
$\tau = 20$



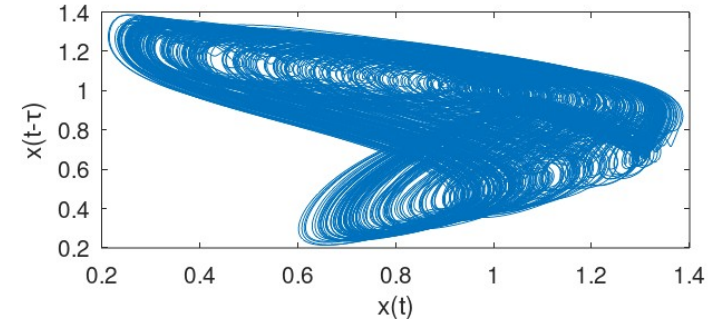
$\lambda_{\max} > 0$



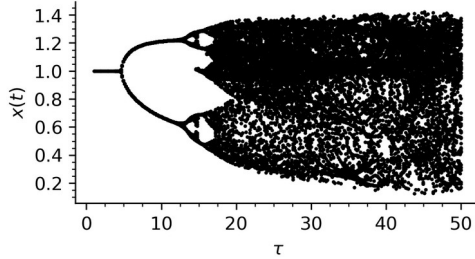
$\tau = 30$



$\lambda_{\max} > 0$

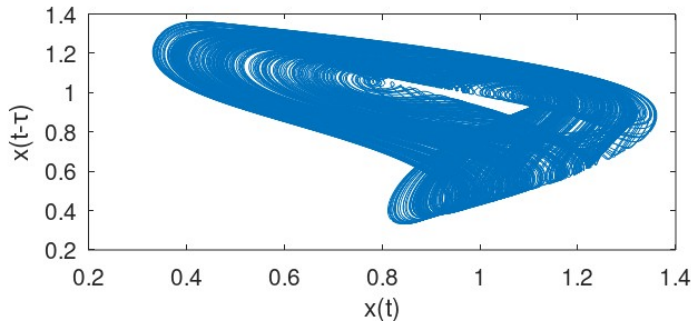


$$\frac{dx}{dt} = \beta \frac{x_\tau}{1 + x_\tau^n} - \gamma x$$

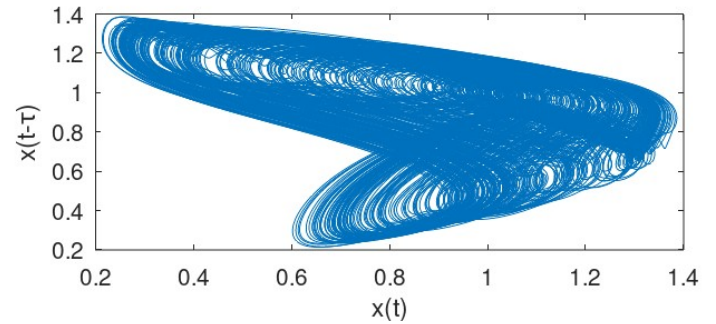


Limit of long delays: phase space volume of chaotic attractor remains unaltered

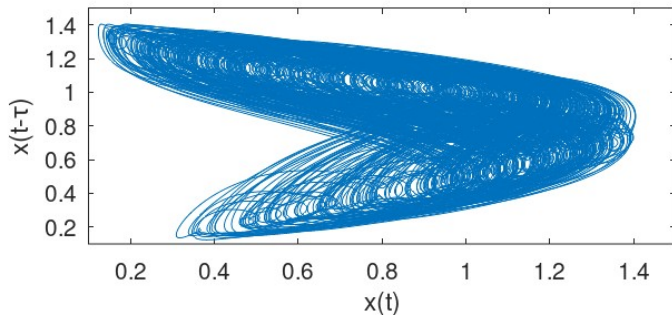
$\tau = 20$



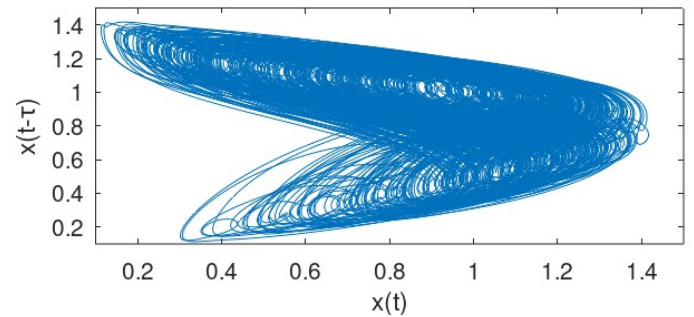
$\tau = 30$



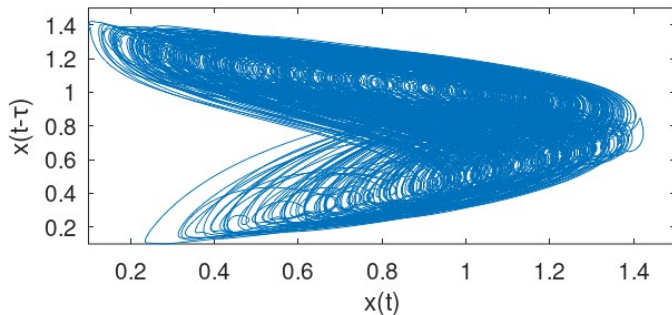
$\tau = 100$



$\tau = 300$

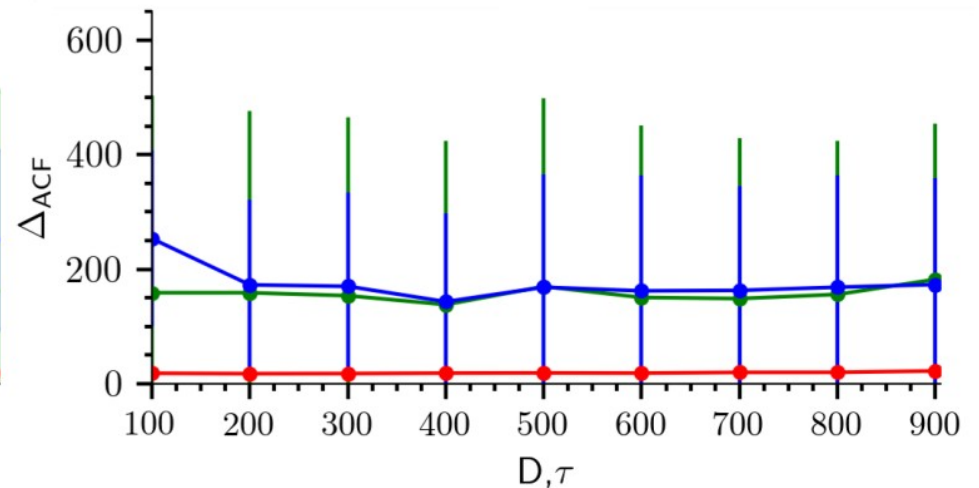
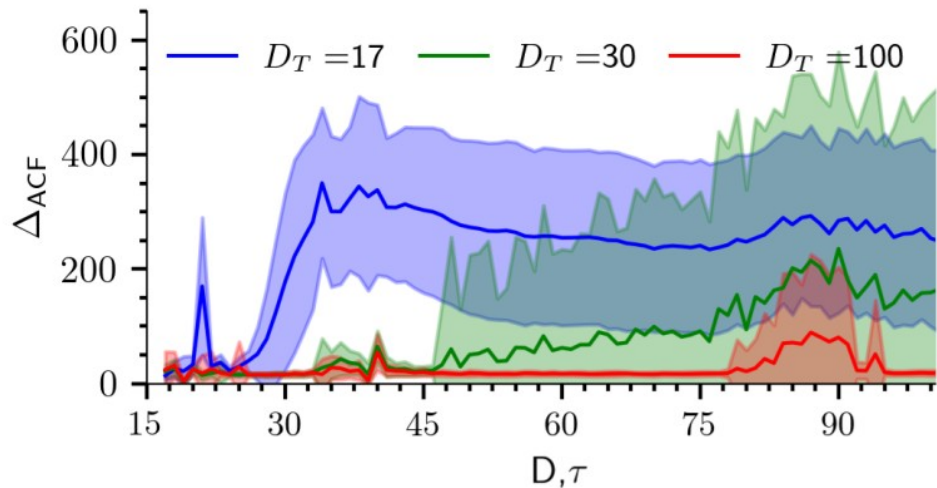


$\tau = 600$



$$\tau \gtrsim 10 \frac{1}{\gamma} \quad (\text{condition long delay } \tau \sim 100)$$

Autocorrelation function difference $\Delta_{ACF} = \sum_i |ACF_{MG} - ACF_{dESN}|$

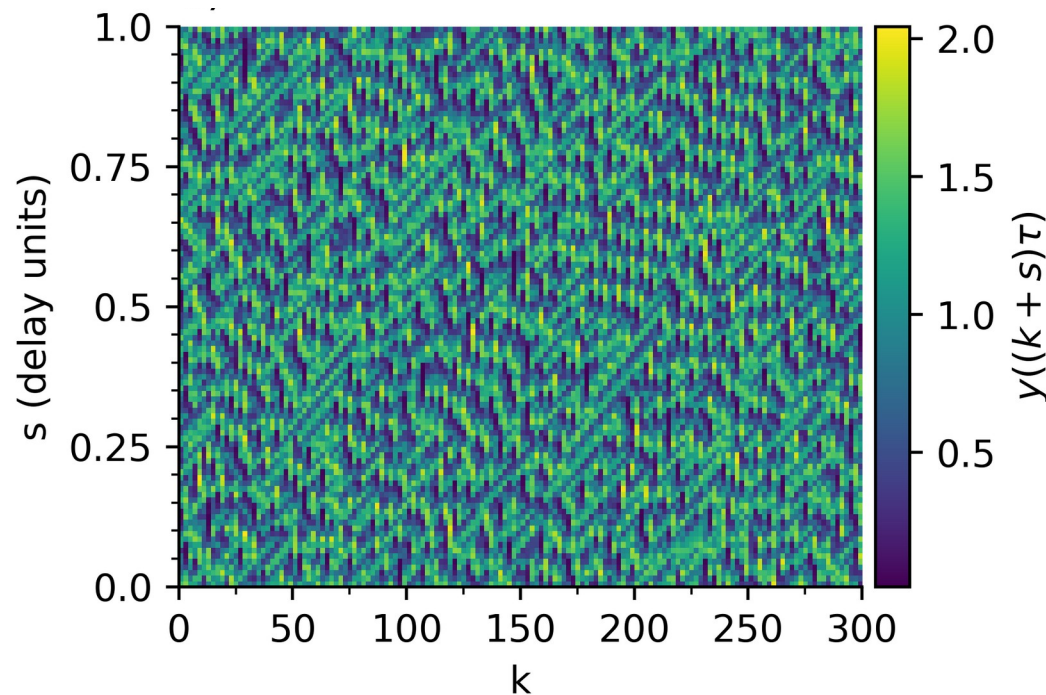


- Training for long delays ($D, \tau = 100$) \rightarrow inference works for short and long delays
- Training for short delays ($D, \tau = 17$ or 30) \rightarrow inference works in the neighborhood of the training example

Knowledge of the dynamical properties useful for ML!

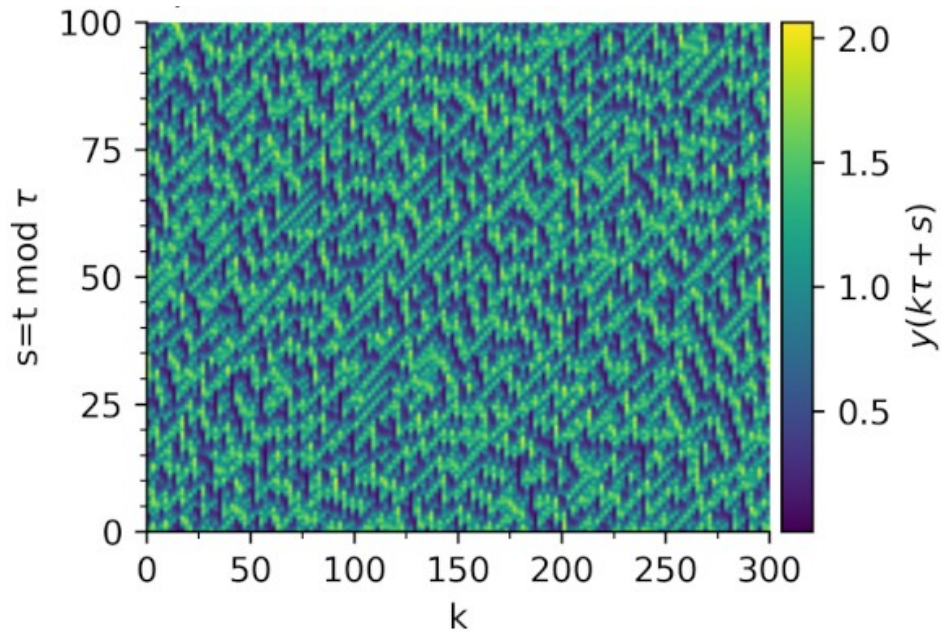
Time Translational Symmetry in Delay Systems

- dynamics of the system do not change over time
- using the quasi-space representation
 - → dynamics are independent along quasi-space s



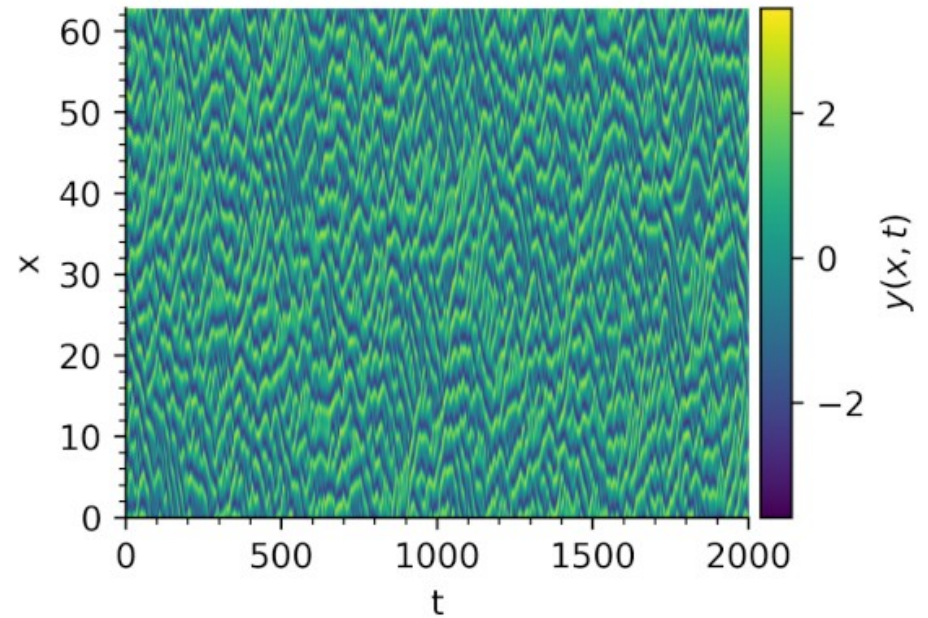
$$\dot{y}(t) = -y(t) + 3y(t - 100)/(1 + y(t - 100)^{10})$$

Analogy: Delay systems - 1D Spatially Extended systems



Mackey-Glass model

$$\dot{y}(t) = -y(t) + 3y(t - 100)/(1 + y(t - 100)^{10})$$

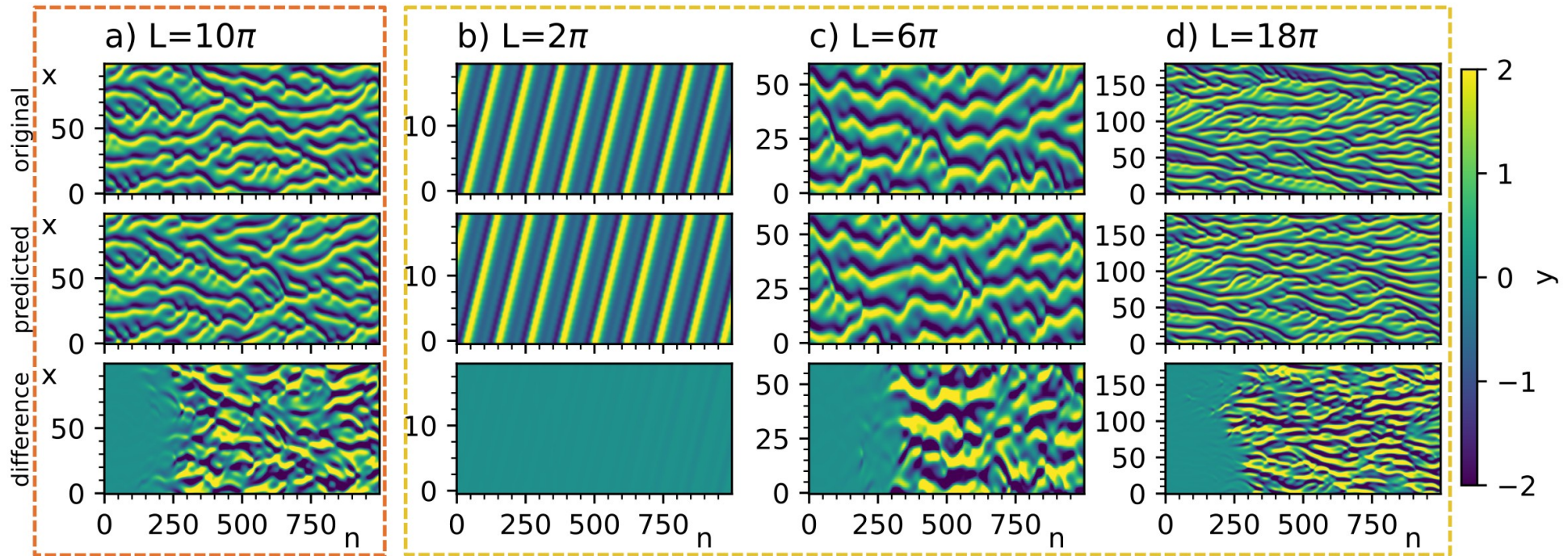


Kuramoto Sivashinsky model

$$y_t = -yy_x - y_{xx} - y_{xxxx},$$

where $y(x, t)$ is a scalar field

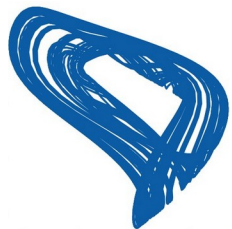
Inferring untrained dynamics of a Kuramoto Sivashinsky model



- Learning one spatial extension and exploiting spatial translational symmetry enables to infer the dynamics for other spatial extensions (assuming periodic boundary conditions)
- Importance of symmetries → analogy between delay and spatio-temporal systems

- **Symmetries** can be used for far reaching inferences of dynamical systems with adapted neural networks
 - Infer unseen/**untrained dynamical regimes**
- → High **generalization ability**
- **Informed machine learning** methods can tackle highly complex dynamical systems
- Plenty of **room for novel findings** at the interface between machine learning and dynamical systems

THANK YOU



M. Goldmann et al., "Inferring untrained complex dynamics of delay systems using an adapted echo state network", arxiv:2111.03706

